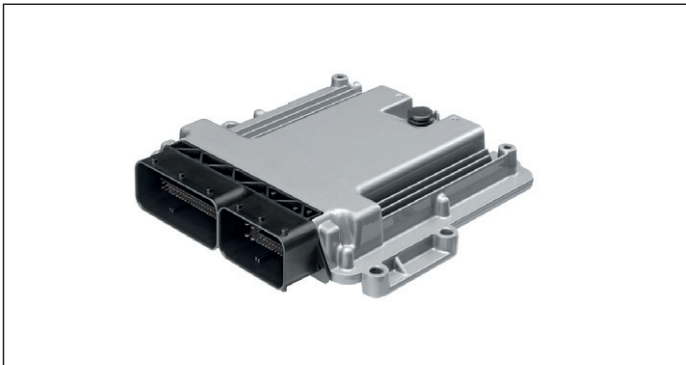


# **BODAS Controller RC**

## **Serie 30**

### **RC28-14, RC20-10, RC12-10**



- For closed- and open-loop control of hydraulic components

#### **Features**

- High performance thanks to ultra-modern 32-TriCore technology with 180 MHz
- Component of BODAS system for mobile applications
- Robust design meeting specifications for mobile applications
- High electromagnetic compatibility (EMC)
- Inputs and outputs with fault detection
- Central deactivation of all outputs
- Pulse-width-modulated (PWM) solenoid currents for minimum hysteresis
- Closed-loop control of solenoid currents, i.e., not dependent on voltage and temperature

#### **Main components**

- Watchdog processor for program run monitoring
- Hardware-based RAM memory supervision
- CPU-internal Flash with ECC error-correcting code
- Three independent sensor power supplies
- Four independent CAN bus interfaces
- Two-channel stop function

#### **Contents**

|                       |    |
|-----------------------|----|
| Ordering code         | 2  |
| Optional accessories  | 2  |
| Description           | 3  |
| Block circuit diagram | 4  |
| Technical data        | 5  |
| Connection diagram    | 7  |
| Connection variants   | 10 |
| Overview of functions | 11 |
| Dimensions            | 17 |
| Installation position | 18 |
| Mating connector      | 19 |
| Safety information    | 21 |

## Ordering code

|           |    |           |
|-----------|----|-----------|
| 01        | 02 | 03        |
| <b>RC</b> |    | <b>30</b> |

### Type

|    |                  |           |
|----|------------------|-----------|
| 01 | BODAS controller | <b>RC</b> |
|----|------------------|-----------|

### Version

|    |  |  |
|----|--|--|
| 02 | 1st number: number of proportional outputs<br>2nd number: number of switched outputs | <b>28-14</b><br><b>20-10</b><br><b>12-10</b> |
|----|--|--|

### Series

|    |                   |           |
|----|-------------------|-----------|
| 03 | Series 3, index 0 | <b>30</b> |
|----|-------------------|-----------|

### Notes:

- ▶ The BODAS controllers are not functional without software.
- ▶ In order to use the BODAS controllers, you also need:
  - BODAS standard software or
  - application-specific software
- ▶ If there is a sample label on the name plate, it is a prototype or sample, i.e., components not released for serial production.  
Possible sample labels are:
  - SC: A
  - SC: B
  - SC: C
  - SC: S (Software prototypes)

## Optional accessories

### ▶ BODAS-design software

The windows-based BODAS-design PC software (data sheet 95112) is used for programming the BODAS RC controllers. All graphical and textual programming languages specified according to IEC 61131-3 are available for the programming.

### ▶ BODAS-service software

The windows-based BODAS-service PC software (data sheet 95086) is used for displaying functions, errors and system variables as well as for setting parameters via a PC.

### ▶ C programming interface C-API

The C-API (data sheet 95115) programming interface is used for programming the BODAS RC controllers in the C programming language. All required functions that are needed for the configuration and the reading of the inputs, the control of the outputs, the use of the communication interfaces and the creation of the diagnostics information for BODAS-service are available to the user.

Additionally, the user needs a C-compiler, with which the created program is translated into a machine code that is readable for the BODAS controller.

### ▶ BODAS MA6 measuring adapter

The BODAS MA6 measuring adapter (data sheet 95090) facilitates measuring all electrical signals at the inputs, outputs and interfaces of the BODAS controller. For testing purposes, it is connected in series between the control unit and the vehicle or device wiring.

### ▶ BODAS TB3 test box(2 pieces) and adapter kit (1 piece)

The BODAS TB3 test box (data sheet 95092) is used for simulation of vehicle and device functions for development and testing purposes with BODAS controllers. The BODAS TB3 test boxes are connected to the control unit via the adapter TAK4/10 .

All products mentioned here are available from Bosch Rexroth. Further information can be found on the internet at: [www.boschrexroth.com/mobile-electronics](http://www.boschrexroth.com/mobile-electronics)

## Description

These BODAS controllers RC are designed as universal central control units for complex mobile working machines. Thanks to the ultra-modern 32-bit TriCore technology, a clock frequency of 180 MHz and parallel processing, these control units push into completely new performance dimensions that were previously reserved for larger PLC systems. The fields of application extend from the programmable control of proportional solenoids and additional switching functions to travel drives and transmission control as well as coordination of highly complex control circuits in mobile working machines. With 75 input channels, up to 42 output stages, four voltage outputs ( $25\% \cdot V_{\text{bat}}$  to  $75\% \cdot V_{\text{bat}}$ ), an additional analog output (4 to 20 mA) as well as four CAN buses for communication in the vehicle, these control units provide a high-performance platform for all functions of mobile working machines.

Internally, the series 30 BODAS RC controllers contain a high performance 32-bit TriCore microprocessor and all input and output circuits. Analog voltages in the range from 0 to 10 V and 0 to 32 V, currents from 0 to 20 mA, frequencies from 0 to 10 kHz and switching information are processed as input signals. In addition, these control units offer special inputs for intelligent Bosch Rexroth sensors, such as the DSM1-10 speed sensor with integrated diagnostics function or resistor inputs from 10 to 2000  $\Omega$ , for example for the direct connection of temperature sensors. The inputs are protected against overvoltage and electrical interference. The voltage inputs can be monitored to detect any cable breaks or short circuits. The current-controlled proportional solenoid outputs are pulse-width-modulated (PWM) and are compensated for fluctuating temperature and voltage for high accuracy and minimum hysteresis. They are optimally harmonized with the electrical proportional control of the axial piston units and valves of Bosch Rexroth. The switching outputs are designed for direct switching of relays and switching solenoids. Moreover, the outputs have integrated voltage and current monitoring.

CAN-bus interfaces are included in all BODAS RC controllers for exchanging data with other bus users or electronic systems (e.g. RC, joystick, diesel engine injection, display). Each of the four independent CAN bus interfaces can be operated using different protocols.

Communication with the BODAS-design and BODAS-service software is likewise done via CAN bus and is based on the Standard Key Word Protocol 2000 (KWP 2000).

Simple and flexible programming of the BODAS controller according to the industry standard IEC 61131-3, which enables a very convenient and rapid introduction to the programming of the controller, is possible with the BODAS-design software. Comprehensive and complex applications can be conveniently developed and clearly represented with BODAS-design.

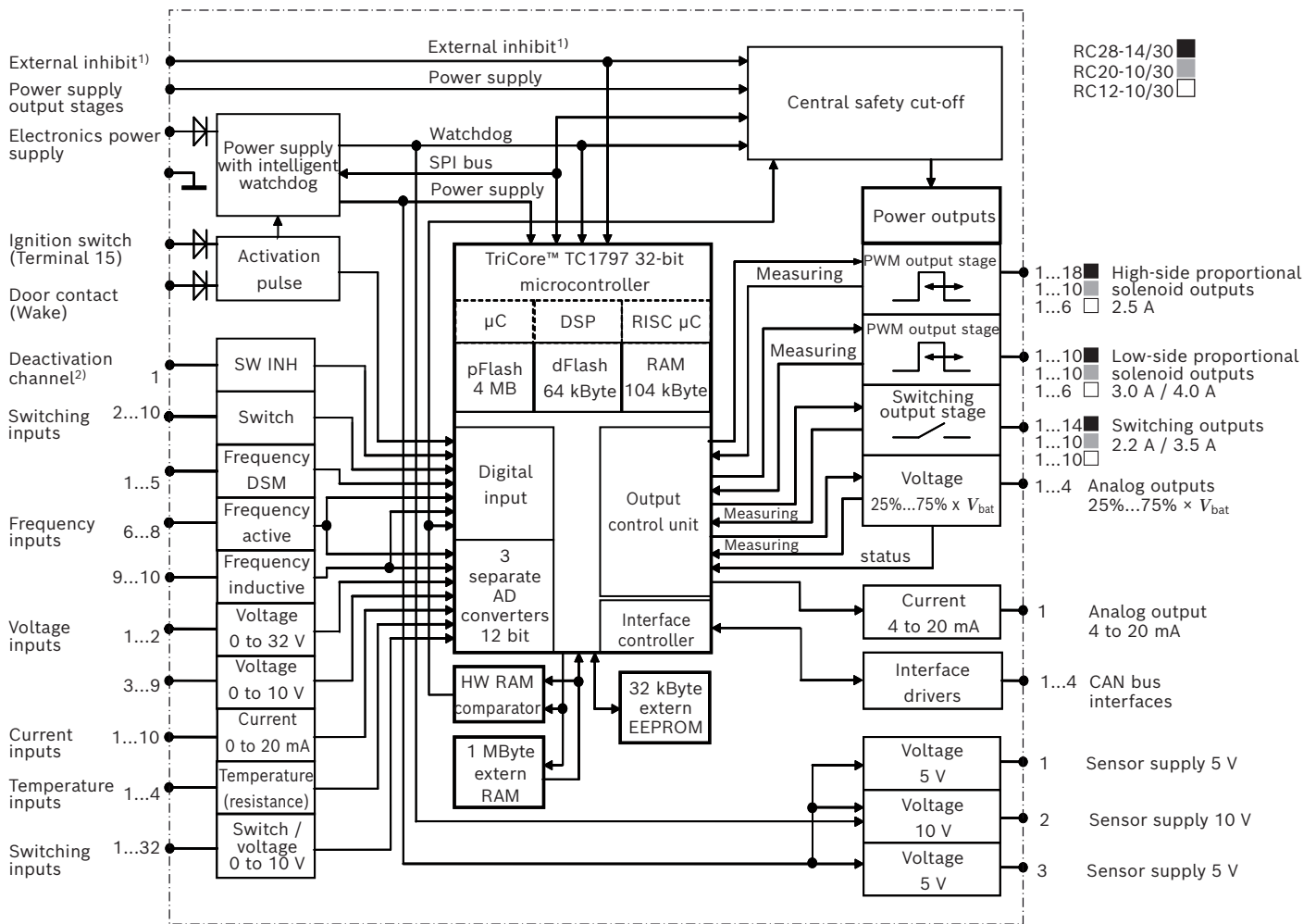
An application interface in the form of a C-API interface is available for the development of the full performance capability of these BODAS controllers when the C programming language is used. By using the C-API, the software developer can concentrate on the important functions of his machine without having to become immersed in the details of the TriCore technology.

With the BODAS-service software, the programs can be quickly and easily downloaded to the control unit via the Flash module. Extensive service functions, such as diagnostics, parameter setting or display of process variables, are available via the graphical Windows interface of BODAS-service. This allows simple parameter setting and diagnostics in order to place the machine in service quickly and safely.

The BODAS RC controllers were developed specifically for use in mobile working machines and satisfy corresponding protection requirements regarding ambient temperatures, water and dust ingress, shock and vibration as well as electromagnetic compatibility (EMC).

BODAS RC controllers and corresponding software in combination with pumps, motors, valves, sensors, input devices and actuators from Bosch Rexroth make for complete system solutions.

Safety-relevant project planning instructions (95451-01-B for EN ISO 13849 and 95452-01-B for ISO 25119) have to be observed for the planning and implementation of safety functions and the two-channel stop function. These are available from Bosch Rexroth on request.

**Block circuit diagram**

- 1) Input that is independent of the microcontroller, for the central enabling/deactivation of the power outputs.
- 2) Input for the central enabling/deactivation of the power outputs.

| Abbreviations |                                  |
|---------------|----------------------------------|
| µC            | microcontroller                  |
| DSP           | digital signal processor         |
| RISC          | reduced instruction set computer |

## Footnotes for page 5

- 1) Exception: GND, GND sensor, constant voltage sources and temperature inputs to battery.
- 2) Max. total current per group: 5 A
- 3) Sensor voltage inputs are raised when there is a short circuit to battery. A correct reading of sensor signals is no longer ensured. Connected sensors may be damaged.
- 4) Line protection. The wiring has to be rated according to the fuse protection.
- 5) Some functions do not comply fully with the respective specification at supply voltage < 11 V. See also overview of functions.

## Technical data

| Controllers RC   |   | 28-14 | 20-10             | 12-10 |
|--|---|-------|-------------------|-------|
|  |   | ■     | ■                 | □     |
| <b>Nominal voltage</b>   | 12 and 24 V   |       | ●                 |       |
| Residual ripple (DIN 40839, part 1)                                      | max. $\pm 2$ V  |       | ●                 |       |
| Supply voltage, permissible range  | 8 to 32 V   |       | (●) <sup>5)</sup> |       |
| <b>Current consumption</b>   |   |       |                   |       |
| standby, in the 12 V vehicle electrical system                           | 380 mA  |       | ●                 |       |
| standby, in the 24 V vehicle electrical system                           | 290 mA  |       | ●                 |       |
| loaded, in the 12 V vehicle electrical system                            | max. 40 A   |       | ●                 |       |
| loaded, in the 24 V vehicle electrical system                            | max. 40 A   |       | ●                 |       |
| <b>Fuses</b>   |   |       |                   |       |
| internal:  |   |       | –                 |       |
| external: in the supply path <sup>4)</sup>                               | 5 A (electronics), maximum 35 A (power outputs)   |       | ●                 |       |
| <b>Controllers enabling pin</b>  | Terminal 15 / Wake  |       | ●                 |       |
| <b>Constant voltage sources<sup>3)</sup></b>                             |   |       |                   |       |
| e.g. for setpoint potentiometer  |   |       |                   |       |
| 150 mA   | 5 V $\pm$ 150 mV  |       | ●                 |       |
| 250 mA   | 5 V $\pm$ 250 mV  |       | ●                 |       |
| 1000 mA  | 10 V $\pm$ 500 mV   |       | ●                 |       |
| <b>Digital inputs</b>  |   |       | 9                 |       |
| <b>Digital voltage inputs</b> , diagnostics capable                      |   |       | 32                |       |
| <b>Analog voltage inputs</b> , pulldown                                  | 0 to 10 V   |       | 7                 |       |
|  | 0 to 32 V   |       | 2                 |       |
| <b>Analog current inputs</b> , diagnostics capable                       | 0 to 20 mA  |       | 10                |       |
| <b>Resistor inputs</b>   |   |       |                   |       |
| e.g. for temperature sensors resistance measuring range                  | 10 to 2000 $\Omega$   |       | 4                 |       |
| <b>Frequency inputs total</b>  |   |       | 10                |       |
| DSM  | 0 to 9 kHz  |       | 5                 |       |
|  | Level: 7 mA/14 mA   |       |                   |       |
| Inductive sensors  | 0 to 10 kHz, Level: $> 1 V_{RMS}$   |       | 2                 |       |
| Active sensors   | 500 Hz to 10 kHz  |       | 3                 |       |
|  | level low: $< 1$ V  |       |                   |       |
|  | level high: $> 4$ V   |       |                   |       |
| <b>Analog signal outputs total</b>                                       |   |       | 5                 |       |
| for 200 $\Omega$ load (ohmic resistance)                                 | 4 to 20 mA  |       | 1                 |       |
| for 150 $\Omega$ load (ohmic resistance)                                 | 0 V (off), 0.1 to 5.0 V   |       |                   |       |
| for 12 k $\Omega$ load (ohmic resistance)                                | 0 V (off), 0% * $V_{bat}$ to 90% * $V_{bat}$<br>(typically 25% * $V_{bat}$ to 75% * $V_{bat}$ ) |       | 4                 |       |
| <b>Proportional solenoid outputs (PWM) total</b>                         |   | 28    | 20                | 12    |
| High side current range  | 0 to 2.5 A  | 18    | 10                | 6     |
| Pulsation frequency  | 0; 50 to 250 Hz   |       |                   |       |
| Low side current range   | 0 to 3.0 A  | 8     | 8                 | 4     |
|  | 0 to 4.0 A  | 2     | 2                 | 2     |
| Pulsation frequency  | 0; 50 to 250 Hz and 1000 Hz   |       |                   |       |
| <b>Digital output stages total</b>                                       |   | 14    | 10                | 10    |
| High side current range  | max. 2.2 A  | 10    | 6                 | 6     |
| High side current range  | max. 3.5 A <sup>2)</sup>  | 4     | 4                 | 4     |
| <b>Interfaces</b>  |   |       | 4                 |       |
| CAN 2.0 B, ISO 11898   |   |       |                   |       |
| <b>Fault detection in the event of cable break and short circuit</b>     |   |       |                   |       |
| Analog inputs  |   |       | ●                 |       |
| Proportional solenoid outputs  |   |       | ●                 |       |
| Switching solenoid outputs   |   |       | ●                 |       |
| <b>Short circuit resistance when energized</b>                           |   |       |                   |       |
| to supply voltage and ground for all inputs and outputs <sup>1) 3)</sup> |   |       | (●)               |       |

See page 4 for footnotes

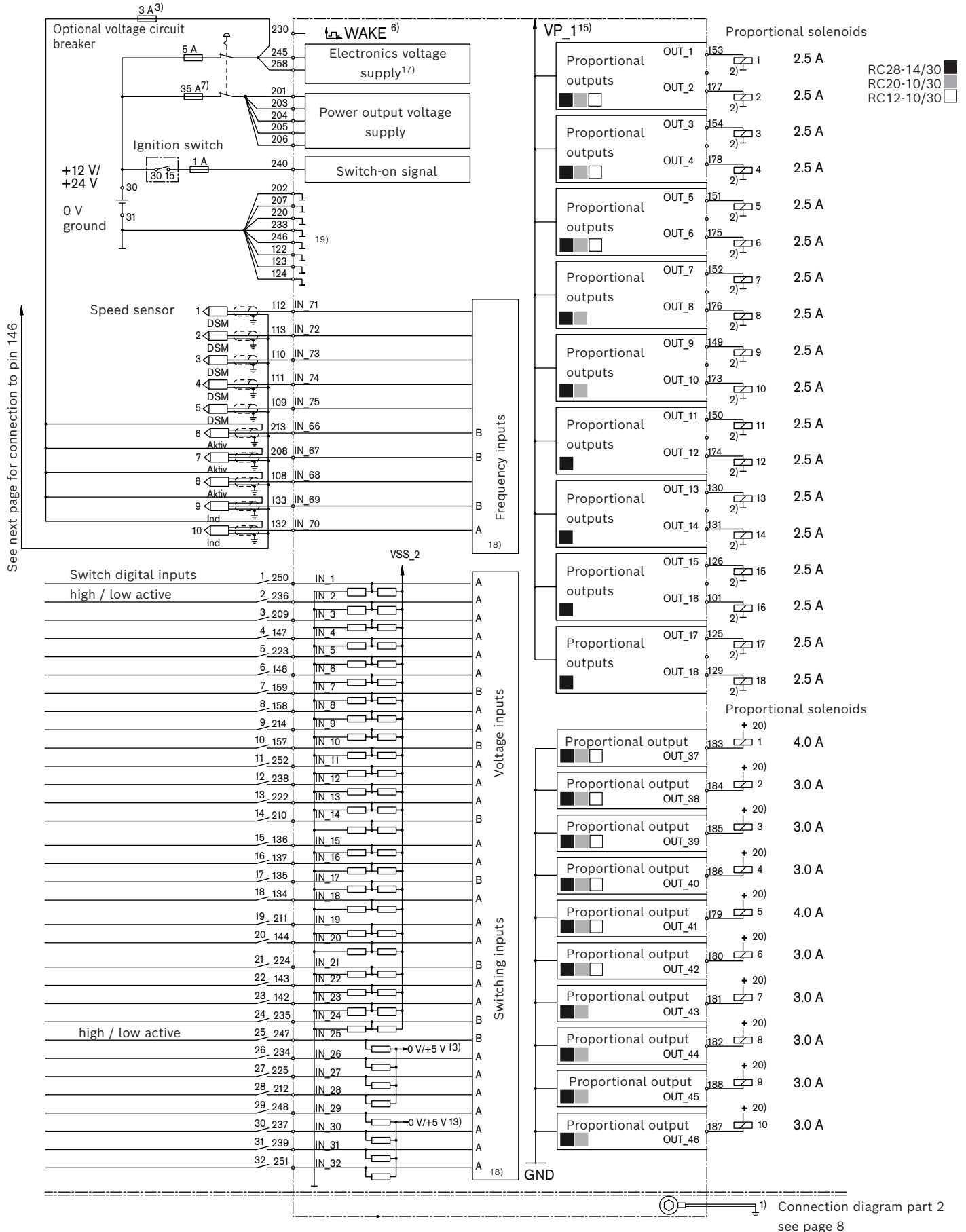
| Controllers RC   |  | 28-14  | 20-10 | 12-10 |
|--|--|--|-------|-------|
|  |  | ■  | ■     | □     |
| <b>Reverse polarity protection<sup>1)</sup></b>                              |  |  |       |       |
| Power supply/battery   |  | –  |       |       |
| <b>Microcontroller</b>   |  | SAK-TC1797   |       |       |
| <b>Clock frequency</b>   | MHz  | 180  |       |       |
| <b>Memory capacities</b>   |  |  |       |       |
| RAM  | MByte  | 1  |       |       |
| Flash EPROM  | MByte  | 4  |       |       |
| EEPROM   | kByte  | 32   |       |       |
| <b>Software installation</b>   |  |  |       |       |
| Download to flash memory   |  | ●  |       |       |
| <b>Electromagnetic compatibility<sup>3)</sup></b>                            |  |  |       |       |
| Spurious interference (ISO 11452-2)  | 150 V <sub>RMS</sub> /m  | ●  |       |       |
| Spurious interference (ISO 11452-5)  | 200 V <sub>RMS</sub> /m  | ●  |       |       |
| <b>Electrostatic discharge ESD (according to ISO 10605)</b>                  |  |  |       |       |
| Out of service   | 8 kV   | ●  |       |       |
| In service   | 15 kV  | ●  |       |       |
| <b>Max. power dissipation</b>  |  |  |       |       |
| Electronics  | W at 32 V  | 8.5  |       |       |
| Output stages  | W at 32 V  | 60   |       |       |
| <b>Operating temperature, housing</b>  |  |  |       |       |
| with mounting point on cooling surface                                       | -40 °C to +85 °C<br>(-40 °C to +185 °F)  | ●  |       |       |
| Maximum temperature of the cooling surface                                   | +60 °C (140 °F)  |  |       |       |
| <b>Storage temperature, housing</b>  |  |  |       |       |
|  |  | Maximum permissible housing temperature in the short-term passive:<br>-40 °C to +105 °C (-40 °C to +221 °F)  |       |       |
| <b>Vibration resistance</b>  |  |  |       |       |
| Broadband noise vibration<br>(ISO 16750-3)                                   | 34 m/s <sup>2</sup> , 10 to 1000 Hz,<br>32 h per axis<br>10 Hz: 18 (m/s <sup>2</sup> ) <sup>2</sup> /Hz<br>20 Hz: 36 (m/s <sup>2</sup> ) <sup>2</sup> /Hz<br>30 Hz: 36 (m/s <sup>2</sup> ) <sup>2</sup> /Hz<br>180 Hz: 1 (m/s <sup>2</sup> ) <sup>2</sup> /Hz<br>2000 Hz: 1 (m/s <sup>2</sup> ) <sup>2</sup> /Hz | ●  |       |       |
| <b>Shock resistance</b>  |  |  |       |       |
| Transport shock<br>(IEC 60068-2-27)  | $a = 400 \text{ m/s}^2$ ; $t = 6 \text{ ms}$<br>per spatial axis x, y, z and in each direction<br>(pos./neg.)  | ●  |       |       |
| <b>Moisture resistance</b><br>(IEC 60068-2-30Db; variant 2)                  |  | 95% (25 °C to +55 °C)  |       |       |
| <b>Salt spray resistance</b><br>(IEC 60068-2-52, test Kb)                    |  | 4x 2 h salt spray (5% NaCl)<br>22 h at 40 °C/93% rF constant environment<br>72 h at storage room temperature |       |       |
| <b>IP rating (DIN EN 60529)<sup>2)</sup></b> with assembled mating connector |  | IP65   |       |       |
| <b>Housing material</b>  |  |  |       |       |
| Cover:   | Diecast aluminum   |  |       |       |
| Base:  | Deep-drawing aluminum  | ●  |       |       |
| <b>Weight</b>  |  | approx. kg   |       |       |
| <b>Outer dimensions</b>  |  |  |       |       |
|  |  | Length (in mm)   |       |       |
|  |  | 204.5  |       |       |
|  |  | Width (in mm)  |       |       |
|  |  | 203  |       |       |
|  |  | Height (in mm)   |       |       |
|  |  | 40.5   |       |       |
| <b>Mating connector</b>  |  |  |       |       |
|  |  | 96-pin   |       |       |
|  |  | 1  |       |       |
|  |  | 58-pin   |       |       |
|  |  | 1  |       |       |

1) The external fuse can serve as reverse polarity protection.

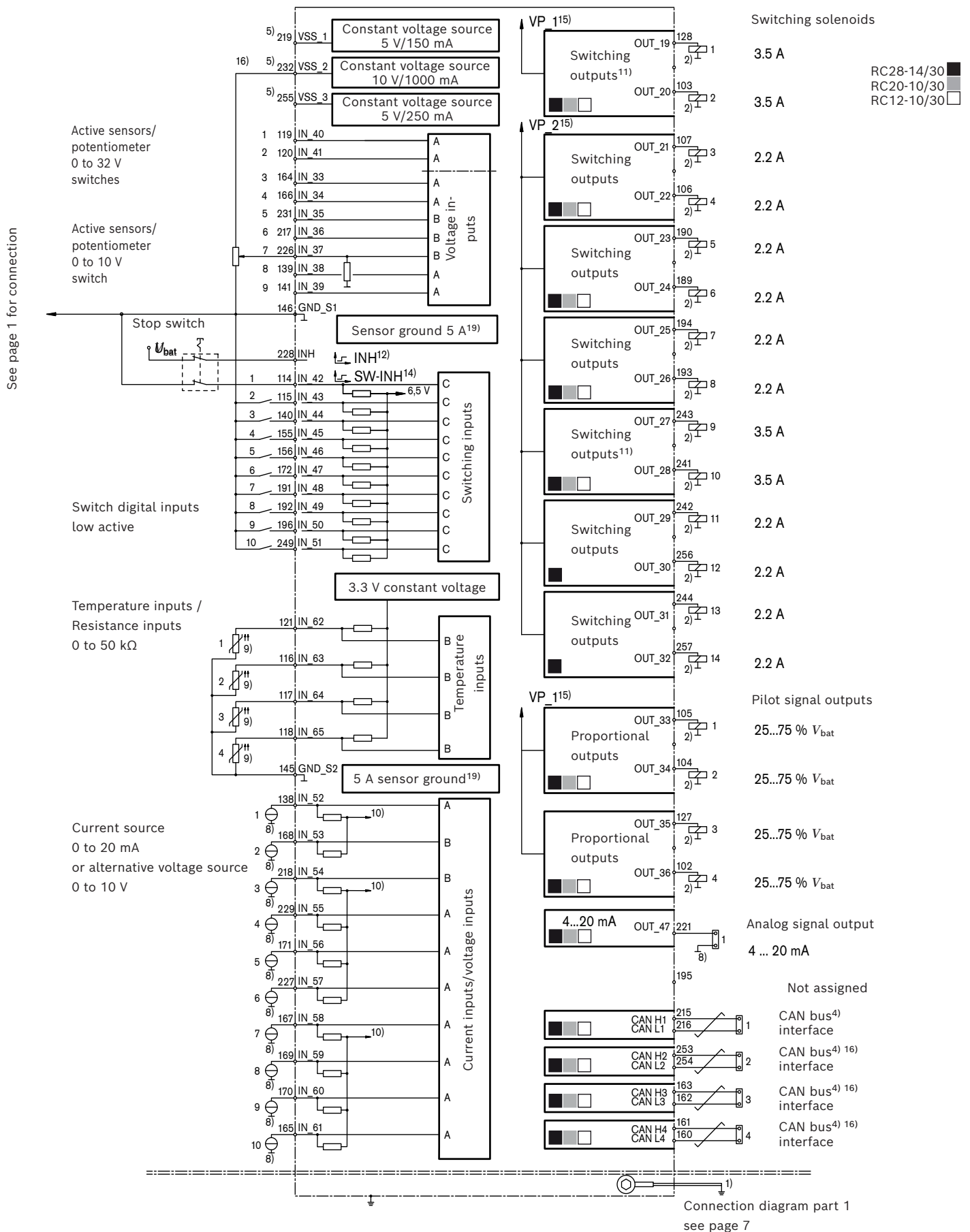
3) Up to 500 kBaud when using the CAN interfaces.

2) While following installation instructions.

## Connection diagram









## Footnotes for pages 7 and 8

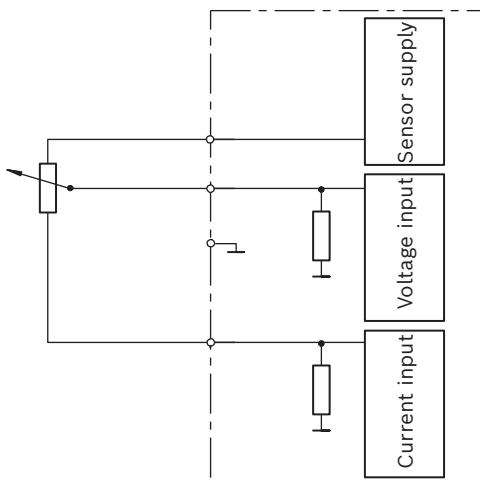
- 
- |  |   |
|--|---|
| <ul style="list-style-type: none"><li>1) Short, low-resistance connection from a housing screw to the vehicle ground.</li><li>2) Independent ground connection to battery (via chassis possible).</li><li>3) Separate fuse required for switches and sensors. Sensor supply application specific.</li><li>4) CAN bus: 120 <math>\Omega</math> termination resistor and twisted pair wire required.</li><li>5) 5 V/10 V outputs can also be used as sensor supply.</li><li>6) Temporary wake up of the control unit when a signal &gt; 8 V is applied for more than 1 sec.</li><li>7) Note max. current consumption with simultaneous actuation of proportional solenoids and switching outputs.</li><li>8) Separate ground connection for current source to the battery, control unit GND possible</li><li>9) Can be used as switching inputs if externally switched to GND.</li><li>10) For use as voltage inputs (0 to 10 V), the internal ohmic resistance can be switched by the software in groups for these inputs.<br/>Groups: inputs 1 to 2, inputs 3 to 6, inputs 7 to 10.</li><li>11) Outputs arranged in groups with 2 output stages each. Maximum permissible output current per group: 5 A</li><li>12) Primary deactivation channel for proportional and switch outputs: enabling with level &gt; 4.5 V, deactivation with level &lt; 1 V, cable break leads to deactivation.</li></ul> | <ul style="list-style-type: none"><li>13) Input groups may be switched to pull down or pull up in software.</li><li>14) Secondary deactivation channel for proportional and switch outputs:<br/>enabling with level &lt; 0.7 V, deactivation with level &gt; 2 V, cable break leads to deactivation.</li><li>15) Supply can be switched by the software.</li><li>16) Shuts off on response from watchdog.<br/>Temporarily interrupted for diagnostic purposes when turning on the main switch for the first time.</li><li>17) If disabled during operation, data will not be saved to the non-volatile memory and there will be no after-run.</li><li>18) A, B and C indicate different A/D converters which may be selected for redundancy reasons.</li><li>19) Terminal 31 (supply ground) and sensor ground are bridged at a star point in the control unit and connected to the housing.</li><li>20) Loads on low-side outputs should be supplied by high-side outputs so that they can also be disabled in the event of a short circuit to ground. See "Safety outputs" in the API manual. If this is not possible, the power must be routed through a relay switched via Terminal 15. In this case, the lines must be equipped with fuses. Connecting directly to Terminal 30 is not permitted.</li></ul> |
|--|---|

## Connection variants

### Monitored potentiometer 2.5 to 5 k $\Omega$

#### Fault monitoring of the potentiometer

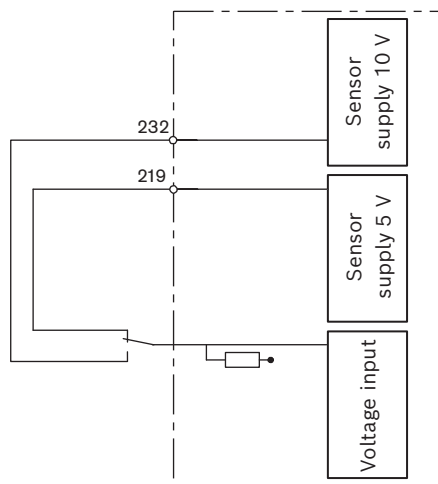
- Internal measurements of the sensor supply voltage (5 V)
- Connection of the potentiometer to a current input, via which the current of the potentiometer is checked.
- Checking the loop voltage. It must be within a valid range (software).



### Switching input with fault detection

#### Fault monitoring of the switching inputs

- Switching of the input voltage between 10 V and 5 V
- Reading the switching level and checking the valid range (software)



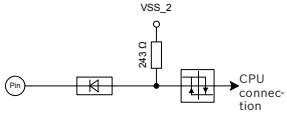
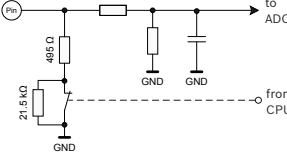
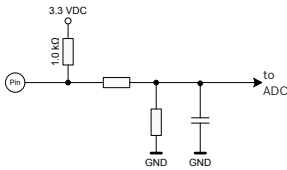
## Overview of functions

| Pin  | Description  | Main function  | Alternative functions  |
|--|--|--|--|
| 250, 236, 209, 147, 223,<br>148, 159, 158, 214, 157,<br>252, 238, 222, 210, 136,<br>137, 135, 134, 211, 144,<br>224, 143, 142, 235 | <b>Digital input</b><br>IN_1 to IN_24<br><br>15 kΩ pull-up resistance to VSS_2 sensor supply <sup>1)</sup> and 5.6 kΩ pull-down resistance to ground | <b>Digital input</b><br>Switching threshold configurable via software (max. 10 V)<br>Externally switchable to GND, VSS_x or V <sub>bat</sub> .<br><br>If V <sub>bat</sub> = 24 V then max. 10 of these inputs may be switched to 24 V simultaneously.                              | <b>Analog voltage input</b><br>Measuring range: 0 to 10 V<br>Resolution: 12 bit (2.7 mV/bit)<br>Input resistance<br>DC to GND: 5.6 kΩ<br>DC to VSS_2: 15.0 kΩ<br>Filter frequency limit: 330 Hz<br><br>Limited diagnostics of cable breakage due to fixed pull-up and pull-down resistance |
| 247, 234, 225, 212<br>248, 237, 239, 251   | <b>Digital input</b><br><br>Pull-up/pull-down resistance can be switched between 5V/ground in two groups<br><br>IN_25 to IN_28<br><br>IN_29 to IN_32 | <b>Digital input</b><br>Switching threshold configurable via software (max. 10 V)<br>Externally switchable to GND, VSS_x or V <sub>bat</sub> .<br><br>Open terminal voltage:<br>Pull-up: 3.5 V<br>Pull-down: 0 V (default)   | <b>Analog voltage input</b><br>Input resistance with pull-up configuration: 21 kΩ to 5 V and 50 kΩ to GND<br>Input resistance with pull-down configuration: 15 kΩ to GND<br>Filter frequency limit: 330 Hz   |
| 164, 166, 231, 217, 226,<br>139, 141   | <b>Analog voltage input</b><br>IN_33 to IN_39  | <b>Analog voltage input</b><br>Measuring range: 0 to 10 V<br>Resolution: 12 bit (2.71 mV/bit)<br>Input resistance<br>DC to GND: 15 kΩ<br>Filter frequency limit: 330 Hz  | <b>Digital input active high</b><br>Evaluation options:<br>Switching threshold configurable via software (max. 10 V)<br><br>Externally switchable to VSS_x   |
| 119, 120   | <b>Analog voltage input</b><br>IN_40 to IN_41  | <b>Analog voltage input</b><br>Measuring range: 0 to 32 V<br>Resolution: 12 bit (8.8 mV/bit)<br>Input resistance<br>DC to GND: 15 kΩ<br>Filter frequency limit: 800 Hz   | <b>Digital input active high</b><br>Evaluation options:<br>Switching threshold configurable via software (max. 32 V)<br><br>Externally switchable to VSS_x or V <sub>bat</sub>   |
| 114  | <b>Digital input</b><br>IN_42 (SW INH)<br><br>21.5 kΩ pull-up resistor to 6.5 V  | <b>Secondary inhibit input</b><br>Activation of output stages:<br>Level low < 0.7 V (switch to GND with low resistance)<br>Deactivation of output stages:<br>Level high > 2 V, ≤ V <sub>bat</sub> (switch open)<br><br>Cable break leads to the deactivation of all output stages. | <b>Digital input active low</b><br>Evaluation options:<br>Digital switching thresholds<br>Level low < 0.7 V (switch to GND with low resistance)<br>Level high > 2 V (switch open)<br><br>Filter frequency limit: 100 Hz  |

1) When V<sub>bat</sub> ≥ 11 V, VSS\_2 = 10 V; when V<sub>bat</sub> < 11 V, VSS\_2 = V<sub>bat</sub> - 1 V

| Pin   | Description  | Main function   | Alternative functions  |
|---|--|---|--|
| 115, 140, 155, 156, 172, 191, 192, 196, 249 | <b>Digital input</b><br>IN_43 to IN_51<br><br>21.5 k $\Omega$ pull-up resistor to 6.5 V  | <b>Digital input active low</b><br>Evaluation options:<br><br>Digital switching thresholds<br>Level low < 0.7 V<br>(switch to GND with low resistance)<br>Level high > 2 V<br>(switch open)<br><br>Filter frequency limit: 100 Hz   |  |
| 213, 208                                    | <b>Active frequency input</b><br>IN_66 to IN_67<br><br>6.8 k $\Omega$ pull-up resistor to VSS_2 <sup>1)</sup> and 24 k $\Omega$ pull-down resistor to ground | <b>Frequency input for Type NPN active sensors</b><br><br>Frequency evaluation of active speed sensors that switch to ground.<br><br>Frequency evaluation up to 10 kHz<br><br>Phase measuring between IN_66 (Pin 213) and IN_67 (Pin 208)<br><br>Short circuit current up to 1.4 mA | <b>Low active digital input</b><br>Evaluation options:<br><br>Switching threshold configurable via software (max. 5 V), accuracy $\pm 0.25$ V<br>Digital switching thresholds<br>Level low < 1 V<br>(switch to GND with low resistance)<br>Level high > 4 V<br>(switch open)<br>Open terminal voltage: > 6 V       |
| 108   | <b>Active frequency input</b><br>IN_68<br><br>6.8 k $\Omega$ pull-up resistor to VSS_2 <sup>1)</sup> and 24 k $\Omega$ pull-down resistor to ground          | <b>Frequency input for Type NPN active sensors</b><br><br>Frequency evaluation of active speed sensors that switch to ground.<br><br>Frequency evaluation up to 10 kHz<br><br>Short circuit current up to 1.4 mA  |  |
| 133, 132                                    | <b>Inductive frequency input</b><br>IN_69 to IN_70<br><br>44 k $\Omega$ pull-down resistance to ground   | <b>Frequency input for Type PNP and NPN inductive and active sensors</b><br>Frequency evaluation: 500 Hz to 10 kHz<br><br>Min. required signal amplitude: 1 $V_{RMS}$ (sine wave)<br>Phase measuring between IN_69 (Pin 133) and IN_70 (Pin 132)                                    | <b>High active digital input</b><br>Evaluation options:<br><br>Switching threshold configurable via software (max. 32 V)<br>(switch to $V_{bat}$ with low resistance)<br>Open terminal voltage: < 1 V<br><br><br><br><br><br>Analog voltage input<br>Measuring range: 0 to 32 V<br>Resolution: 12 bit (7.6 mV/bit) |

1) When  $V_{bat} \geq 11$  V, VSS\_2 = 10 V; when  $V_{bat} < 11$  V, VSS\_2 =  $V_{bat} - 1$  V

| Pin  | Description   | Main function   | Alternative functions   |
|--|---|---|---|
| 112, 113, 110, 111, 109                              | <b>DSM frequency input</b><br>IN_71 to IN_75<br><br> <p>This input has an internal pull-up resistance of 243 Ω to VSS_2 (10 V).</p>  | <b>Frequency input for Rexroth DSM sensors</b><br><br>Frequency evaluation up to 9 kHz<br>Evaluation of additional information, such as direction of rotation and fault monitoring.   | <b>Frequency input for Type NPN active sensors</b><br><br>Frequency evaluation of active speed sensors that switch to ground.<br><br>Level low < 5 V (7 mA)<br>Level high > 9 V (13 mA)<br><br>Phase measuring between IN_71 (Pin 112) and IN_72 (Pin 113)<br>Phase measuring between IN_73 (Pin 110) and IN_74 (Pin 111)<br><br>Attention:<br>Short circuit current to ground up to 40 mA. |
| 138, 168<br>218, 229, 171, 227<br>167, 169, 170, 165 | <b>Analog current input</b><br>with switchable internal ohmic resistance<br>IN_52 to IN_61<br><br> <p>Switchable in three groups between analog current and voltage input</p> <p>IN_52 and IN_53<br/>IN_54 to IN_57<br/>IN_58 to IN_61</p> | <b>Analog current measuring input</b><br>Measuring range: 0 to 20 mA<br>Internal ohmic resistance: 490 Ω<br>Resolution: 12 bit (5.5 µA/bit)<br><br>Filter frequency limit: 330 Hz<br><br>In 12 V applications two current inputs may be connected in parallel to halve the internal ohmic resistance. | <b>Analog voltage input</b><br>Measuring range: 0 to 10 V<br>Resolution: 12 bit (2.71 mV/bit)<br><br>Input resistance<br>DC to GND: 12.38 kΩ<br>Filter frequency limit: 330 Hz<br><br><b>Digital input active high</b><br><br>Evaluation options:<br>Switching threshold configurable via software (max. 10 V)<br>Open terminal voltage: < 1 V  |
| 121, 116, 117, 118                                   | <b>Temperature input</b><br>IN_62 to IN_65<br><br> <p>1 kΩ pull-up resistor to 3.3 V and 150 kΩ pull-down resistor to ground</p> <p>Not short circuit-proof to battery.</p>  | <b>Resistance input</b><br>Measuring range 0 .. 200 kΩ<br><br><b>Temperature input</b><br>Measuring range -50 .. 150 °C<br><br>Can be used with Bosch Rexroth TSA, TSF (PTC) temperature sensors, Bosch NTC temperature sensors or DST sensor.<br>For details see API manual.                         | <b>Digital input active low</b><br>Evaluation options: Switching threshold configurable via software (max. 3.3 V) (switch to GND with low resistance or switch open)<br>Open terminal voltage: > 3 V<br><br><b>Analog voltage input</b><br>Measuring range: 0 to 3 V<br>Resolution: 12 bit (0.8 mV/bit)<br>Filter frequency limit: 230 Hz   |

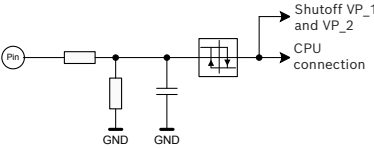
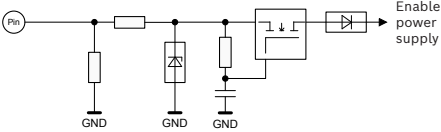
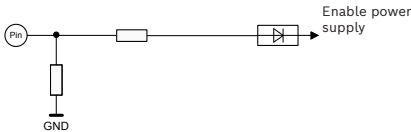
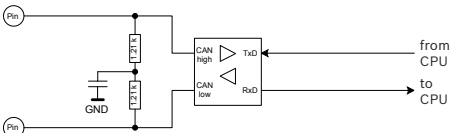
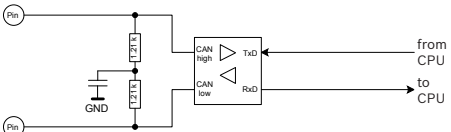
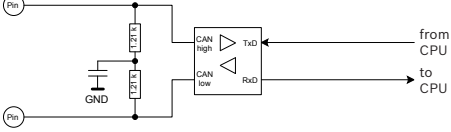
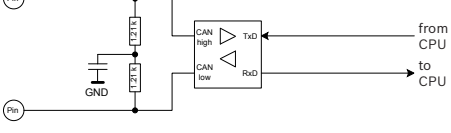
| Pin  | Description   | Main function  | Alternative functions   |
|--|---|--|---|
| 153, 177, 154, 178, 151, 175, 152, 176, 149, 173, 150, 174, 130, 131, 126, 101, 125, 129 | <b>PWM output stage</b><br>OUT_1 to OUT_18                          | <b>PWM output stage</b><br><b>High-side switch</b><br>Clock frequency adjustable via software<br><br>Integrated free-wheeling diode for switching of inductive loads<br>Max. current: 2.5 A<br>Duty factor: 0 to 100%<br>Power supply centrally switchable via VP_1              | <b>Switching output stage</b><br>with diagnostics duty cycle: 100%    |
|  | <b>PWM output stage</b><br>OUT_38 to OUT_40 and<br>OUT_42 to OUT_46 | <b>PWM output stage</b><br><b>Low-side switch</b><br>Clock frequency configurable via software<br><br>Integrated free-wheeling diode for switching of inductive loads<br><br>Max. current: 3.0 A<br>Duty factor: 0 to 100%   | <b>Switching output stage</b><br>with diagnostics<br>Duty cycle: 100% |
|  | <b>PWM output stage</b><br>OUT_37 and OUT_41                        | <b>PWM output stage</b><br><b>Low-side switch</b><br>Clock frequency adjustable via software<br><br>Integrated free-wheeling diode for switching of inductive loads<br><br>Max. current: 4.0 A<br>Duty factor: 0 to 100%<br><br>Maximum current depends on duty factor and load. | <b>Switching output stage</b><br>with diagnostics<br>Duty cycle: 100% |
|  | <b>Analog voltage output</b><br>OUT_33 to OUT_36                    | <b>PWM control voltage</b><br>Output voltage: $0\% \times V_{bat}$ to $90\% \times V_{bat}$<br>(typically $25\% \times V_{bat}$ to $75\% \times V_{bat}$ )<br>400 to 5000 Hz<br><br>OUT_33 to OUT_36:<br>Power supply centrally switchable via VP_1                              |   |
|  |   |  |   |

| Pin  | Description   | Main function  | Alternative functions   |
|--|---|--|---|
| 107, 106, 190, 189, 194, 193, 242, 256, 244, 257 | <b>Switching output stage with current sensing</b><br>OUT_21 to OUT_26 and OUT_29 to OUT_32 | <b>High-side switch switching output stage<sup>1)</sup></b><br>Max. current 2.2 A<br><br>Integrated free-wheeling diode for switching of inductive loads<br><br>Power supply centrally switchable via VP_2                                     |   |
| 128, 103, 243, 241                               | <b>Switching output stage with current sensing</b><br>OUT_19 to OUT_20 and OUT_27 to OUT_28 | <b>High-side switch switching output stage<sup>1)</sup></b><br>Max. current 3.5 A<br><br>Integrated free-wheeling diode for switching of inductive loads<br><br>OUT_19 to OUT_20: switchable via VP_1<br>OUT_27 to OUT_28: switchable via VP_2 |   |
| 221  | <b>Analog signal output</b><br>OUT_47   | <b>Analog current output</b><br>Output signal 4...20 mA with 200 $\Omega$ external ohmic resistance<br>Output powered via VSS_2  | <b>Analog voltage output</b><br>Output signal 0.5 to 5.0 V<br><br>150 $\Omega$ external ohmic resistance to ground required |
| 219  | <b>Sensor supply</b><br>VSS_1   | <b>Sensor supply</b><br>Output voltage 5.0 V<br>Accuracy $\pm 0.15$ V<br>Load capacity 150 mA  |   |
| 232  | <b>Sensor supply</b><br>VSS_2   | <b>Sensor supply, deactivatable</b><br>Output voltage 10.0 V <sup>2)</sup> but not more than $V_{bat} - 1$ V<br>Accuracy $\pm 0.50$ V<br>Load capacity: 1000 mA  |   |
| 255  | <b>Sensor supply</b><br>VSS_3   | <b>Sensor supply, deactivatable</b><br>Output voltage 5.0 V<br>Accuracy $\pm 0.25$ V<br>Load capacity 250 mA   |   |

1) Software configuration as proportional output with 100% duty cycle required.

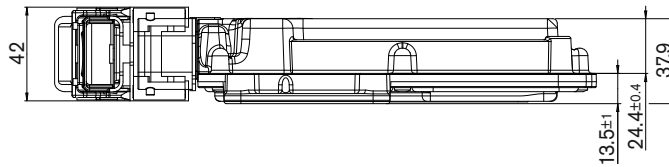
2) When  $V_{bat} \geq 11$  V, VSS\_2 = 10 V; when  $V_{bat} < 11$  V, VSS\_2 =  $V_{bat} - 1$  V



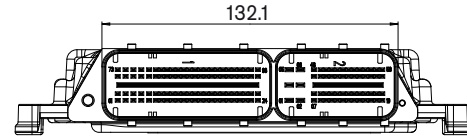
| Pin  | Description  | Main function  | Alternative functions |
|--|--|--|-----------------------|
| <p>228</p>         | <p><b>External inhibit INH</b></p>   | <p><b>Primary inhibit input</b><br/>Activation of the output stages:<br/>Level &gt; 4.5 V, <math>\leq V_{bat}</math><br/>Deactivation of output stages:<br/>Level &lt; 1 V<br/>Cable break leads to the deactivation of all output stages.<br/>Input resistance<br/>DC to GND: 34 k<math>\Omega</math></p> |                       |
| <p>230</p>         | <p><b>Door contact WAKE</b><br/>Enables temporary power up of the control unit</p> | <p><b>Digital input</b><br/>Switch on control unit<br/>Level &gt; 8 V, <math>\leq V_{bat}</math><br/>Input resistance<br/>DC to GND: 18.5 k<math>\Omega</math></p>   |                       |
| <p>240</p>        | <p><b>KL15 ignition switch</b><br/>Power on signal for the control unit</p>        | <p><b>Digital input</b><br/>Controller activation<br/>Level &gt; 8 V, <math>\leq V_{bat}</math><br/>Input resistance<br/>DC to GND: 10 k<math>\Omega</math></p>  |                       |
| <p>215, 216</p>  | <p><b>CAN interface</b><br/>CAN1_H, CAN1_L</p>                                     | <p><b>CAN interface</b><br/>CAN 2.0 B, factory setting 250 kBaud, standard diagnostics interface up to 1 Mbaud, termination resistor in cable harness required</p>   |                       |
| <p>253, 254</p>  | <p><b>CAN interface</b><br/>CAN2_H, CAN2_L</p>                                     | <p><b>CAN interface</b><br/>CAN 2.0 B, up to 1 Mbaud, termination resistor in cable harness required</p>   |                       |
| <p>163, 162</p>  | <p><b>CAN interface</b><br/>CAN3_H, CAN3_L</p>                                     | <p><b>CAN interface</b><br/>CAN 2.0 B, up to 1 Mbaud, termination resistor in cable harness required</p>   |                       |
| <p>161, 160</p>  | <p><b>CAN interface</b><br/>CAN4_H, CAN4_L</p>                                     | <p><b>CAN interface</b><br/>CAN 2.0 B, up to 1 Mbaud, termination resistor in cable harness required</p>   |                       |

**Dimensions**

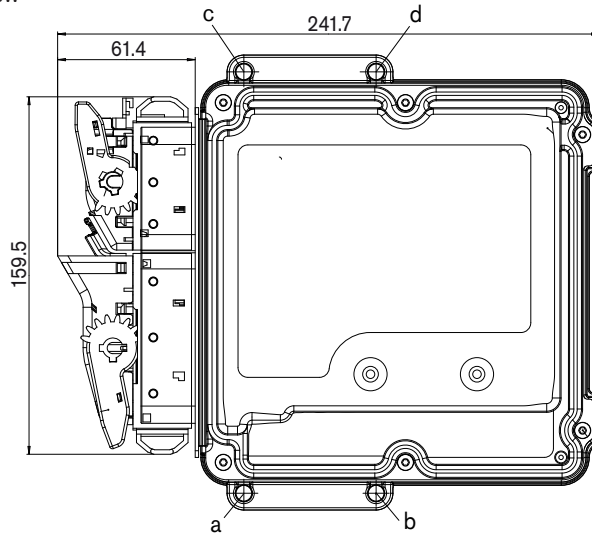
Long-side side view



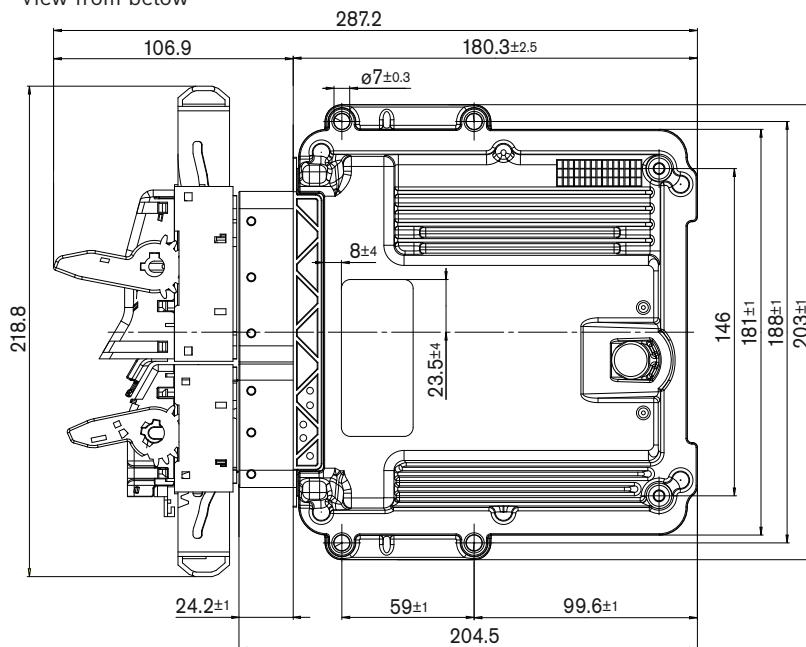
Side view of connector side with pulled connector



Plan view



View from below



## Fixing:

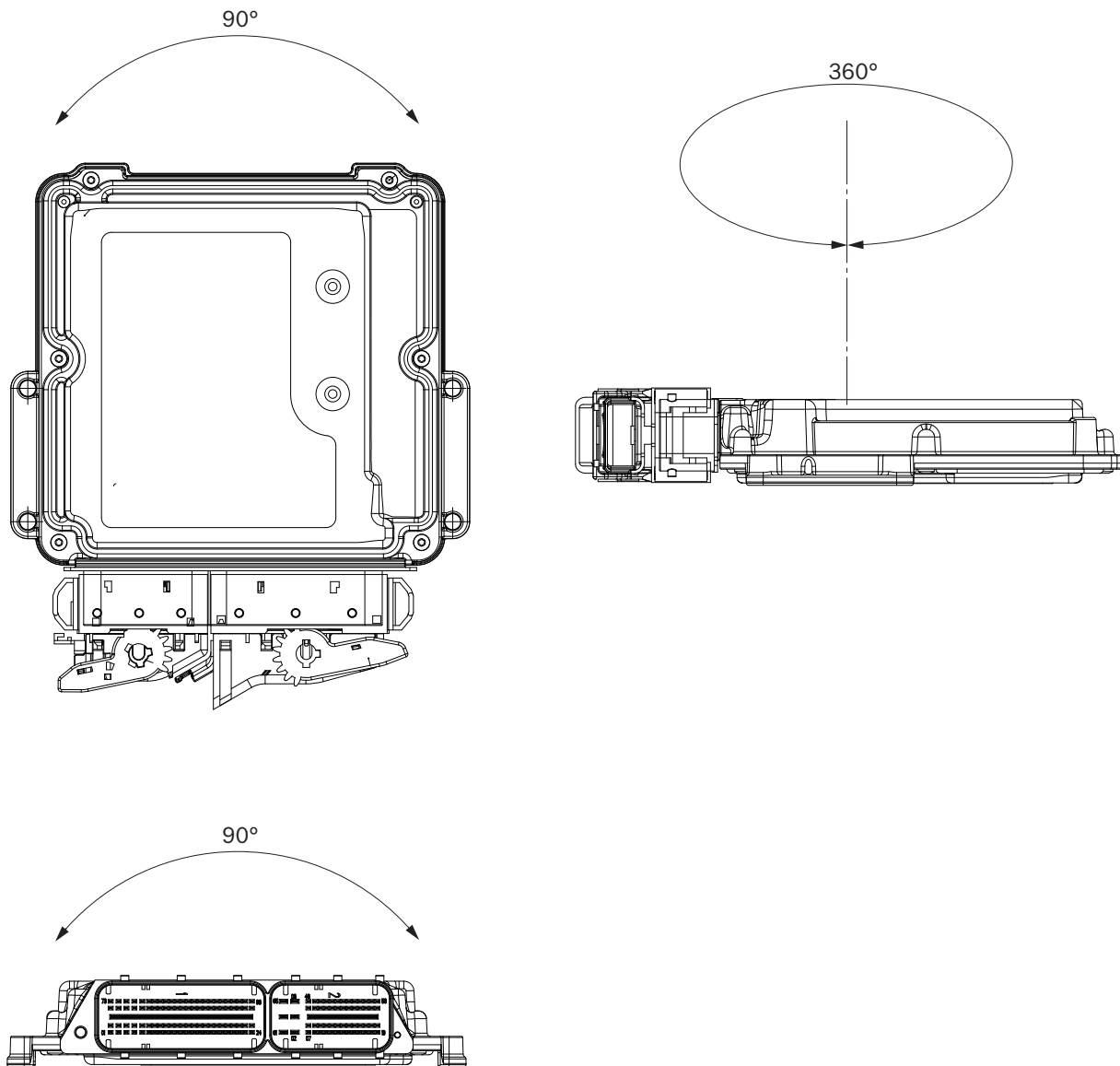
- ▶ The BODAS controller must be fixed at 4 positions (a, b, c and d).
- ▶ Tightening torque  $MA = 8 \pm 2$  Nm for mounting the BODAS control unit with M6 screws.
- ▶ Tightening torque applies for fitting without washer. The equivalent tightening torque must be calculated when using washers.
- ▶ Rexroth's consent is required if fixing is different from above.
- ▶ Installation point: flatness of the mounting surface  $\nabla 0.5$
- ▶ The wiring harness should be mechanically fixed in the area in which the control unit is installed (spacing < 150 mm). The wiring harness should be fixated so that in-phase excitation with the controller occurs (e.g. at the controller mounting points).

If the mounting surface is not sufficiently even, place flexible compensating elements (e.g. rubber washers) between the fixing points of the BODAS controller and the mounting surface.

- ▶ Space required for mating connector
- ▶ Space required for plugging and unplugging the mating connector

Display without scale, dimensions in mm

## Installation position



Note:  
Installation position only permissible with specified angular range.

## Mating connector

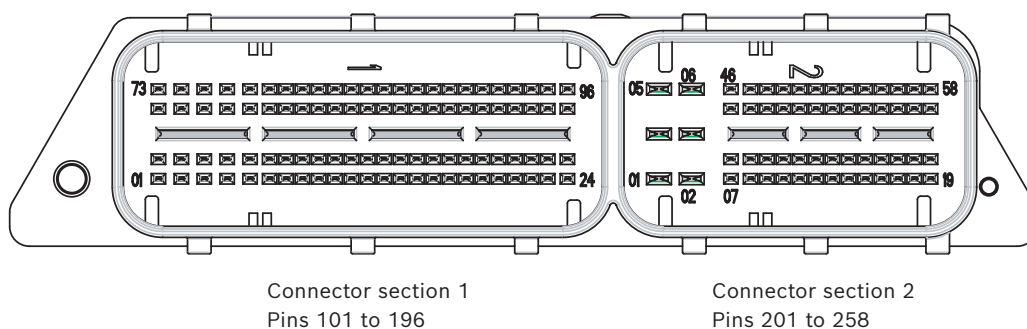
Order designations for the connector set with the Rexroth material number R902603622

| Designation   | Number          | Bosch part numbers of the individual parts |               |
|---|-----------------|--|---------------|
|   |                 | Module 58-pin                              | Module 96-pin |
| Contact carrier code: A   | 1 per connector | 1 928 404 780                              | 1 928 404 781 |
| Cover pre-installed, cable exit left**)   | 1 per connector | 1 928 404 774                              | 1 928 404 773 |
| Secondary lock 1.2  | 1 per connector | 1 928 404 760                              | 1 928 404 762 |
| Secondary lock 2.8  | 1               | 1 928 404 761                              | –             |
| Wire tie (cable tie)  | 1 per connector | 1 928 401 713                              |               |
| <b>Contacts</b><br>BDK 2.8 contact<br>Surface: SN<br>Insulation cross section: 2.2 to 3.0 mm<br>Line cross section: 1.5 to 2.5 mm | 6 (8)*)         | 1 928 498 057                              | –             |
| Matrix 1.2 contact<br>Surface: SN<br>Insulation cross section: 1.2 to 1.6 mm<br>Line cross section: 0.35 to 0.5 mm                | 52 (55)*)       | 1 928 498 679                              | –             |
| Matrix 1.2 contact<br>Surface: SN<br>Insulation cross section: 1.2 to 1.6 mm<br>Line cross section: 0.35 to 0.5 mm                | 96 (100)*)      | –  | 1 928 498 679 |
| <b>Individual sealing</b><br>White for BDK 2.8<br>Cross section: 2.2 to 3.0 mm  | 6 (8)*)         | 1 928 300 600                              | –             |

\*) The number in the brackets indicates how many contacts or individual seals are included in the Rexroth connector set. The number without brackets indicates the requirement.

\*\*) Other variants are available from Bosch. See [www.bosch-connectors.com](http://www.bosch-connectors.com).

## View of connector strip



The control unit connector strip can be ordered separately under Rexroth material number R917009804, e.g., for testing a wiring harness. Delivery only in quantities for lab use.

**Notes regarding assembly**

Please observe the assembly instructions for connectors (1 928 A00 48M) as well as the processing specifications for BDK 2.8 contacts (1 928 F00 025) and Matrix 1.2 contacts (1 928 A00 47M) when assembling the connectors.

These assembly instructions are available from Bosch Rexroth upon request.

**Note**

Please observe the following when assembling the connector in the vehicle:  
The wiring harness must be attached  $\leq 150$  mm from the outgoing wires and at the same vibration level as the control unit.

**Recommended lines**

Recommended connecting lines for contacts 201 to 206:

- ▶ Cross section  $1.5 \text{ mm}^2$  to  $2.5 \text{ mm}^2$   
(16 to 14 AWG, 14 AWG with thin electric insulation)
- ▶ Outer diameter: 2.2 mm to 3.0 mm

Recommended connecting lines for contacts 101-105, 124, 125-129, 148, 149-153, 172, 173-177, 196, 207, 220, 233, 246:

- ▶ Cross section  $1.0 \text{ mm}^2$  to  $1.5 \text{ mm}^2$  (18 to 16 AWG)
- ▶ Outer diameter: 1.9 to 2.1 mm for  $1.0 \text{ mm}^2$ , 2.2 to 2.4 mm for  $1.5 \text{ mm}^2$

Lines with a cross section of  $0.35 \text{ mm}^2$  to  $0.5 \text{ mm}^2$  can also be used for these contacts (see other contacts below). However, the  $1.0 \text{ mm}^2$  to  $1.5 \text{ mm}^2$  cross sections can make it easier to insert the contacts into the connector.

Recommended connection lines for the contacts not mentioned above:

- ▶ Cross section:  $0.35 \text{ mm}^2$  to  $0.5 \text{ mm}^2$  (22 AWG)
- ▶ Outer diameter: 1.2 to 1.6 mm

**Required tools**

Bosch part numbers for tools<sup>1)</sup>

| Designation                                    | Type FLK-R line cross sections                  |   |                    |                    |
|--|---|---|--------------------|--------------------|
|  | BDK 2.8 contacts<br>$1.5$ to $2.5 \text{ mm}^2$ | Matrix 1.2 contacts<br>$0.35$ to $0.5 \text{ mm}^2$ | $1.0 \text{ mm}^2$ | $1.5 \text{ mm}^2$ |
| Contact  | 1 928 498 057                                   | 1 928 498 679                                       | 1 928 498 680      | 1 928 498 681      |
| Crimping tool with matrix                      | 1 928 498 162                                   | 1 928 498 212                                       | 1 928 498 213      | 1 928 498 214      |
| Quick-change tool                              | 1 928 498 164                                   | 1 928 498 720                                       | 1 928 498 722      | 1 928 498 723      |
| Wear parts set                                 | 1 928 498 166                                   | 1 928 498 724                                       | 1 928 498 726      | 1 928 498 727      |
| Disassembly extraction tool                    | 1 928 498 167                                   |   | 1 928 498 218      |                    |
| 10 replacement needles for the extraction tool | 1 928 498 168                                   |   | 1 928 498 219      |                    |

Drawings and further information about Bosch connectors and tools can be found on the internet:  
[www.bosch-connectors.com](http://www.bosch-connectors.com)

<sup>1)</sup> Tools can be ordered from Bosch retailers or Bosch Service ([www.bosch-service.com](http://www.bosch-service.com)).

## Safety information

### General

- ▶ Reliable operation cannot be guaranteed if samples or prototypes are used in series production machines.
- ▶ The proposed circuits do not imply any technical liability for the system on the part of Bosch Rexroth.
- ▶ Incorrect connections could cause unexpected signals at the outputs of the control unit.
- ▶ Incorrect programming or parameter settings on the control unit may create potential dangers while the machine is in operation.  
It is the responsibility of the machine manufacturer to identify hazards of this type in a hazard analysis and to bring them to the attention of the end user. Rexroth assumes no liability for dangers of this type.
- ▶ The component firmware/software must be installed or changed by Bosch Rexroth or by the authorized partner concerned in order to uphold the warranty.
- ▶ It is not permissible to open the control unit or to modify or repair the control unit. Modifications or repairs to the wiring could result in dangerous malfunctions.  
Repairs to the control unit may only be performed by Bosch Rexroth or by an authorized partner.
- ▶ To switch off the system in emergencies, the stop switch (two-channel stop function) or the optional de-energize switch may be used. The switch must be in an easily accessible position for the operator. The system must be designed in such a way that safe braking is ensured when the outputs are switched off.
- ▶ Make sure no pins are connected to a voltage source when the electronics is not powered. Thus, when the current supply is switched off, the supply for the electronics, the output stages and the external sensor supply have to be switched off together.
- ▶ Make sure that the control unit's configuration does not lead to safety-critical malfunctions of the complete system in the event of failure or malfunction. Such system behavior could result in death or serious property damage.
- ▶ System developments, installation and commissioning of electronic systems for controlling hydraulic drives must only be carried out by trained and experienced specialists who are sufficiently familiar with the components used and with the complete system.
- ▶ The machine may cause unforeseen hazards during control unit commissioning and maintenance (with BODAS Tools). Before commissioning the system, you must therefore ensure that the vehicle and the hydraulic system are in a safe condition.

- ▶ Make sure that nobody is in the machine's danger zone.
- ▶ No defective or incorrectly functioning components may be used. If the components should fail or demonstrate faulty operation, repairs must be performed immediately.
- ▶ Controllers used to develop software may only be installed in series production machines if it can be guaranteed that these control units have not been flash-programmed with new software more than 500 times. Controllers that have been programmed more than 1000 are not to be installed in series production machines.

### Notes on the installation point and position

- ▶ Do not install the control unit close to parts that generate considerable heat (e.g. exhaust).
- ▶ Radio transmitting equipment and mobile telephones must not be used in the driver's cab without a suitable antenna or near the control electronics.
- ▶ A sufficiently large distance to radio transmitting systems must be maintained.
- ▶ All connectors must be unplugged from the electronics during electrical welding and painting operations.
- ▶ Cables/wires must be sealed individually to prevent water from entering the device.
- ▶ The control unit must not be electrostatically charged, e.g. during painting operations.
- ▶ The control unit will heat up beyond normal ambient temperature during operation. To avoid danger caused by high temperatures, it should be protected against contact.
- ▶ Install the control unit in such a way that the electrical plug is not facing upwards. This ensures that any condensation water that may form can flow out.
- ▶ Standing and permanently running water are not permitted anywhere near the circumferential groove (lid/base connector) or the pressure balance element (DAE).
- ▶ The housing must be wired to vehicle ground in order to comply with EMC guidelines. Metallic screws are used to create a connection to vehicle ground.
- ▶ The controller must be fixed with metallic screws to provide a good thermal connection between the housing and the cooling surface (heat sink).

## Notes on transport and storage

- ▶ If it is dropped, the control unit must not be used any longer as invisible damage could have a negative impact on reliability.
- ▶ Store control units at an average relative humidity of 60% and at a temperature between -10 °C and 30 °C. Storage temperatures between -20 °C and +40 °C are briefly permissible, for up to 100 hours.
- ▶ After a storage time of more than 5 years, the control unit must be examined by the manufacturer.

## Notes on wiring and circuitry

- ▶ The electronics and the power outputs of a controller must be fed from the same power source.
- ▶ When wiring the output stages, the maximum cumulative output current for each output stage group should be noted. The cumulative output current means a permanent, simultaneous actuation of the output stages.
- ▶ Lines to the speed sensors are to be shielded and kept as short as possible. The shield must be connected to the electronics on one side or to the machine or vehicle ground via a low-resistance connection.
- ▶ The product may only be wired when it is de-energized.
- ▶ Lines to the electronics must not be routed close to other power-conducting lines in the machine or vehicle.
- ▶ The wiring harness should be fixed mechanically in the area in which the control unit is installed (spacing < 150 mm). The wiring harness should be fixed so that in-phase excitation with the control unit occurs (e.g. at the control unit bolting point).
- ▶ If possible, lines should be routed in the vehicle interior. If the lines are routed outside the vehicle, make sure that they are securely fixed.
- ▶ Lines must not be kinked or twisted, must not rub against edges and must not be routed through sharp-edged ducts without protection.
- ▶ Lines are to be routed with sufficient spacing to hot or moving vehicle parts.
- ▶ PWM outputs must not be linked or bridged.
- ▶ PMW outputs (OUT\_1 to OUT\_18 and OUT\_37 to OUT\_46) must not be used to power lamps.
- ▶ The sensor supplies can be “pulled up” by external connection, e.g. the application of a higher voltage, because they operate only as a voltage source but not as a voltage sink! Pulling up a sensor supply may result in unexpected malfunctions and damage the control unit in continuous operation.

- ▶ The “high side” outputs may not be externally connected to battery.
- ▶ If the stop function is used in an application, contact 228 (INH) of the control unit must be connected to the stop switch in the vehicle. For a dual channel switch off function the contact SW-INH has to be connected to the stop switch too. Refer to the connection diagram.
- ▶ The optional voltage disconnecter may not be used to switch the control unit off and on.

## Notes on proportional and switching solenoids and other wired inductive consumers

- ▶ The proportional solenoids must not be wired with free-wheeling diodes.
- ▶ Switching solenoids at control unit outputs do not need to be connected to free-wheeling diodes.
- ▶ The electronics may only be tested with the proportional solenoids connected.
- ▶ Other inductive loads that are in the system but not connected to the control unit must be connected to free-wheeling diodes. This also applies to relays (e.g. for shutting off the control unit) that are powered by the same source as the control unit.

## Intended use

- ▶ The control unit is designed for use in mobile working machines provided no limitations / restrictions are made to certain application areas in this data sheet.
- ▶ Operation of the control unit must generally occur within the operating ranges specified and released in this data sheet, particularly with regard to voltage, current, temperature, vibration, shock and other described environmental influences.
- ▶ Use outside of the specified and released boundary conditions may result in hazard to persons and/or cause damage to components which could result in subsequential damage to the mobile working machine.

## Improper use

- ▶ Any use of the control unit other than as described under “Intended use” is considered to be improper.
- ▶ Use in explosive areas is not permissible.
- ▶ Damage resulting from improper use and/or from unauthorized interference in the component not described in this data sheet render all warranty and liability claims void with respect to the manufacturer.



## Use in functions relevant to safety

- ▶ The customer is responsible for performing risk analysis on the mobile working machine and determining the possible safety-related functions.
- ▶ In safety-related applications, the customer is responsible for taking suitable measures to ensure safety (sensor redundancy, plausibility check, emergency switch, etc.).
  - For example, a suitable assignment of input variables (e.g., by connecting the acceleration pedal signal to two independent analog inputs) can be used to detect faults and to trigger specially programmed reactions.
  - Special measures may be taken if the plausibility check shows deviations between the setpoint values and the values read back from the microcontroller.
- ▶ Product data that is necessary to assess the safety of the machine can be provided upon request or are listed in this data sheet.
  - For all control units, the notes found in the API description, in the online help section of BODAS design and in the “safety-relevant project planning instructions” must be observed.
  - The service life of the control unit may be reduced depending on the conditions in which it is used. See the “safety-relevant project planning instructions” for more information.

## Safety features in the BODAS controller

- ▶ The input circuits for speed and analog signals partially feature circuits that are mutually electrically isolated. Through appropriate input connections, the microcontroller and, when used, the software diagnostic function can detect faults.
- ▶ Faults in the voltage supply are detected by internal monitoring.
- ▶ All output signals can be monitored by the microcontroller with the appropriate software.
- ▶ For service purposes, the control units can be operated with all power outputs de-energized.
- ▶ The internal watchdog module centrally switches off the power supply of all proportional and switched outputs when there are malfunctions in the program run.

## Further information

- ▶ In addition, the application-specific documents (connection diagrams, software descriptions, etc.) are to be observed.
- ▶ More detailed information on BODAS controllers may be found at [www.boschrexroth.com/mobile-electronics](http://www.boschrexroth.com/mobile-electronics)

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