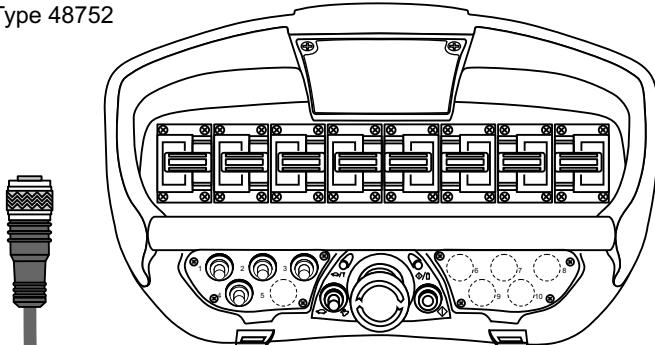


**PORTABLE
CONTROLLER
UNIT**

1A	2A	3A	4A	5A	6A	7A	8A
↑	↑	↑	↑	↑	↑	↑	↑
↓	↓	↓	↓	↓	↓	↓	↓
1B	2B	3B	4B	5B	6B	7B	8B

Type 48752



SWITCH MAP

	left/up	center	right/down
SW1:	1 - 0	-	8
SW2:	2 > 0	< 3	
SW3:	4 > 0	< 5	
SW4:	9 -	-	0

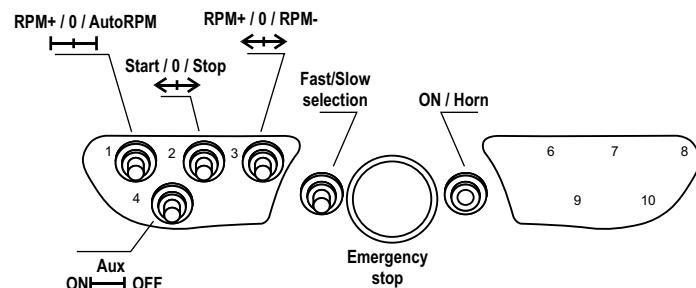
— = detent
↔ >/< = spring return

OUTPUT MAP

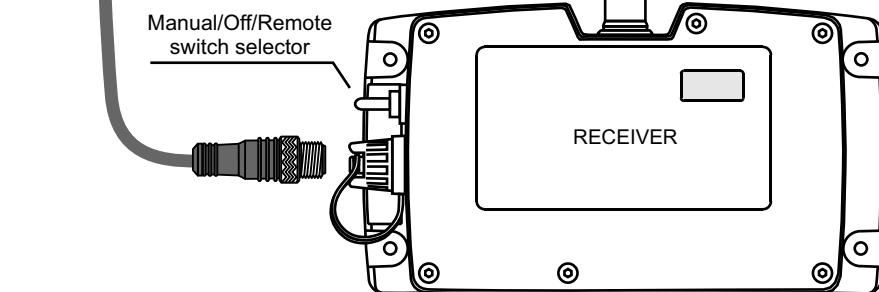
Pos	DF	OUT	Pos	DF	OUT
1	1	1	11	10	12
2	3	2	12	11	13
3	4	3	13	12	14
4	7	4	14	13	-
5	31	5	15	9	-
6	5	6	16	8	-
7	32	-	17	37	-
8	2	9	18	34	-
9	6	10	19	35	-
10	33	11	20	36	-

Clacson/Horn	17	7
Emergency Stop	40	8

Cable used to bypass radio mode or to program the radio remote control L=10m



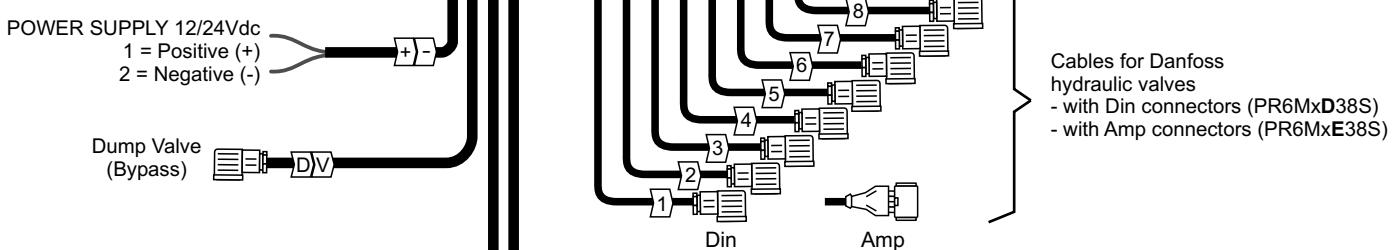
Type 2010



AutoRPM working switch description

When SW1 is on +RPM (left position)
Output Out1 remains always ON.

When SW1 is on AutoRPM (right position)
Output Out9 is ON while output Out1 turns ON only when a proportional lever is not in center. Out1 turns OFF with a 6 seconds delay after all levers have returned in center.



- OUT1 → Ex1.1 - RPM+/AutoRPM
 - OUT2 → Ex1.2 - Start
 - OUT3 → Ex1.3 - Stop
 - OUT4 → Ex1.4 - RPM+
 - OUT5 → Ex1.5 - RPM-
 - OUT6 → Ex1.6 - not used
 - Ex1.7 - negative
 - DIN1 → Ex1.8 - not used
 - DIN2 → Ex1.9 - not used
 - DIN3 → Ex1.10 - WMB selection
 - Ex1.11 - positive in REMOTE
- Collegare insieme nella versione Base (x="B")

- Single supply for Danfoss modules
- DV delay = 0.5 s
- The "Emergency stop" output (Out8) is active (positive) only when the PCU is on.

B=Crane
C=WMB
U=only SET1
D=Din conn.
E=Amp conn.

SW: vedi tabella template

SCANRECO
SOUTH EUROPE
Radio Remote Control

CODICE:

PR6Mxy38S

DESC: Scanreco RC400 G2B radio remote control global view for Danfoss with maxi PCU

FILE: \G2B\Produzione\Danfoss\maxi\PR6Mxy38S_ie.cdr

DATA: 20/03/14

FOGLIO

1

DI

1

WMB = WorkMan Basket
WMB mode (Ex1.10 wire not connected)
speeds are reduced (SET2) and single-function system.