Variable displacement axial piston pump type V60N

Product documentation



Open circuit, for the power take-off of commercial vehicles

Nominal pressure $p_{\text{nom max}}$: 400 bar Peak pressure p_{max} : 450 bar Displacement volume V_{max} : 130 cm³/rev







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1

Overview: variable displacement axial piston pump type V60N

Variable displacement axial piston pumps adjust the geometric output volume from maximum to zero. As a result they vary the flow rate that is provided to the consumers.

The variable displacement axial piston pump type V60N is designed for open circuits in mobile hydraulics and operates according to the swash plate principle. It is available with the option of a thru-shaft for operating with additional hydraulic pumps in series.

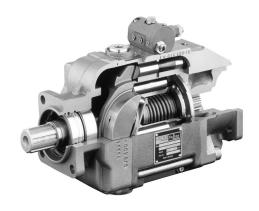
The pump is mostly mounted on power take-offs in commercial vehicle gearboxes. The range of pump controllers allows the axial piston pump to be used in a variety of applications.

Features and benefits

- Optimized power-to-weight ratio
- Broad selection of controllers
- Slim design matching PTO (power take-off)
- Thru-shaft compatibility
- High self-suction speed

Intended applications

- Municipal trucks
- Fire trucks
- Loading cranes and elevating work platforms
- Tipper trucks and skip trucks
- Suction dredgers and sewer cleaning vehicles



Variable displacement axial piston pump type V60N-95



Variable displacement axial piston pump type V60N-130



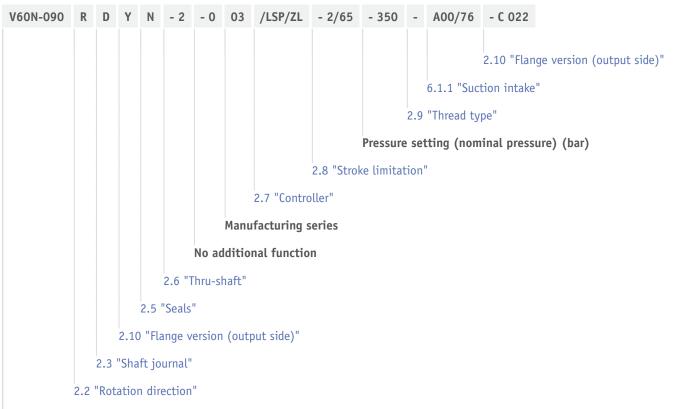
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Available versions

Circuit symbol



Ordering example



2.1 "Basic type and nominal size"

2.1 Basic type and nominal size

Coding	displacement volume V _{max} (cm ³ /rev)	Nominal pressure pnom max (bar)	Peak pressure p _{max} (bar)
060	60	350	400
090	90	350	400
110	110	350	400
130	130	400	450



2.2 Rotation direction

Coding	Description
L	Anti-clockwise
R	Clockwise

2.3 Shaft journal

Coding	Description	Designation/standard	Max. drive torque (Nm)
D	Parallel key splined shaft	Similar to DIN ISO 14 (for HGV) B8x32x35	800
М	Spline shaft	W30x2x14x9g DIN 5480 (only V60N-090, V60N-110)	530
Н	Spline shaft	SAE-B J 744 13T 16/32 DP 22-4 DIN ISO 3019-1 (only V60N-060)	210
U	Spline shaft	SAE-B J 744 short 13T 16/32 DP 22-4 DIN ISO 3019-1 short (only V60N-060)	210
Т	Spline shaft	SAE-BB J 744 15T 16/32 DP 25-4 DIN ISO 3019-1 (only V60N-060)	340
S	Spline shaft	SAE-C J 744 14T 12/24 DP 32-4 DIN ISO 3019-1	640
Q	Spline shaft	SAE-CS 21T 16/32 DP 35-4 DIN ISO 3019-1 (only V60N-090, V60N-110, V60N-130)	900

2.4 Flange version (input side)

Coding	Description	Designation
Υ	Flange	DIN ISO 7653 (for HGV)
P	Flange	DIN ISO 7653 - turned through 10° (for HGV) (only V60N-110, V60N-130) *
х	Flange	SAE-B 2-hole J 744 - 45° rotated 101-2 DIN ISO 3019-1 (only V60N-060)
Z	Flange	SAE-B 4-hole J 744 101-4 DIN ISO 3019-1 (only V60N-060)
F	Flange	SAE-C 4-hole J 744 127-4 DIN ISO 3019-1
G	Flange	125 B4 HW DIN ISO 3019-2 (only V60N-090, V60N-110)

^{*} In particularly tight installation situations, a flange that is turned by 10° can be used to prevent a collision with the cardan shaft.



2.5 Seals

Coding	Description
N	NBR (gearbox-side shaft seal made of FKM, pump-side shaft seal and other NBR seals)
V	FKM



When switching on the pump, the transmission-side oil must be warmer than -25 $^{\circ}\text{C}$.

2.6 Thru-shaft

Coding	Description
1	Suction and pressure connection axial
2	Suction and pressure connection radial, with thru-shaft
3	Suction and pressure connection radial
4	Suction and pressure port axial, ports SAE J 518 (only V60N-090)

2.7 Controller

Load-sensing controller

Coding	Description
LSP	Load-sensing controller with integrated pressure limitation (Standard version for combination with hydraulic valves that relieve the LS signal in the valve, for example, type PSV proportional directional spool valve see Chapter 2.7.1, "Load-sensing controller LSP, LSPT"
LSPT	Load-sensing controller with integrated pressure limitation and additional LS relief (only for use with hydraulic valves without their own relief of the LS signal) see Chapter 2.7.1, "Load-sensing controller LSP, LSPT"
LSNR	Load-sensing controller with integrated pressure limitation. Discontinued type; use coding LSP for new projects. (Version for combination with hydraulic valves that relieve the LS signal in the valve, for example, type PSV proportional directional spool valve see Chapter 2.7.2, "Load-sensing controller LSNR, LSNRT"
LSNRT	Load-sensing controller with integrated pressure limitation and additional LS relief. Discontinued type; use coding LSPT for new projects. (only for use with hydraulic valves without their own relief of the LS signal) see Chapter 2.7.2, "Load-sensing controller LSNR, LSNRT"

Delivery flow controller

Coding	Description
QP/	Flow controller with integrated pressure limitation for setting a constant flow rate independently of the speed. see Chapter 2.7.3, "Delivery flow controller QP"
ZV	Size 060 , 090 , 110 : Electro-proportional delivery flow controller with increasing characteristic curve (intermediate plate) Only in combination with a pressure controller (coding NR2) see Chapter 2.7.4, "Flow controller ZV, ZV1 and V"



Coding	Description
ZV1	Size 060 , 090 , 110 : Electro-proportional delivery flow controller with decreasing characteristic curve (intermediate plate). Only in combination with a pressure controller (coding NR2). see Chapter 2.7.4, "Flow controller ZV, ZV1 and V"
V	Size 130 : Electro-proportional delivery flow controller with increasing characteristic curve. Only in combination with a pressure controller (coding NR3) see Chapter 2.7.4, "Flow controller ZV, ZV1 and V"

Pressure controller

Coding	Description
NR	Mechanically adjustable pressure controller (standard version). see Chapter 2.7.5, "Pressure controller NR, NR2, NR3"
NR2	Mechanically adjustable pressure controller. Only in combination with type ZV, ZV1 flow controllers. see Chapter 2.7.5, "Pressure controller NR, NR2, NR3"
NR3	Mechanically adjustable pressure controller. Only in combination with type V flow controllers. see Chapter 2.7.5, "Pressure controller NR, NR2, NR3"
PR	Electro-proportional pressure controller with increasing characteristic curve. Cannot be combined with other pump controllers! see Chapter 2.7.6, "Pressure controller PR, P1R"
P1R	Size 060 , 090 , 110 : Electro-proportional pressure controller with falling characteristic curve. Cannot be combined with other pump controllers! see Chapter 2.7.5, "Pressure controller NR, NR2, NR3"

Power controller

Coding	Description
ZL	Size 060 , 090 , 110 : Power controller (intermediate plate) Only in combination with a flow controller or pressure controller see Chapter 2.7.7, "Power controller ZL and L"
L	Size 130 : Power controller (as standard) Only in combination with a flow controller or pressure controller see Chapter 2.7.7, "Power controller ZL and L"

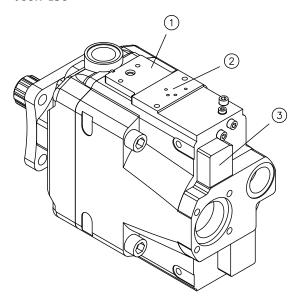
Intermediate plate

Coding	Description
ZW	Size 060, 090, 110: 45° angle intermediate plate Standard for housing versions -2 and -3, to avoid a collision between the pump controller and the suction or pressure line Only in combination with a flow controller or pressure controller see Chapter 2.7.8, "ZW intermediate plate"



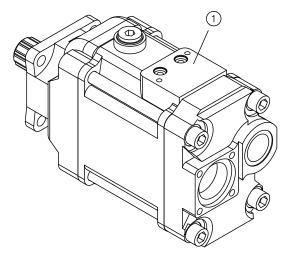
Assembly

V60N-130



- 1 Type L controller mounting point
- 2 Type LSP, LSPT, LSNR, LSNRT, QP, NR, NR3, PR, ZW controller mounting point
- 3 Type V controller mounting point

V60N-060/090/110



1 Type LSP, LSPT, LSNR, LSNRT, QP, NR, NR2, PR, P1R, ZL, ZW controller mounting point



2.7.1 Load-sensing controller LSP, LSPT

The LSP and LSPT controllers are flow controllers that generate a variable, speed-independent flow rate. They adapt the displacement volume of the pump to the required flow rate of the consumer and regulate a constant difference between load pressure and pump pressure.

The integrated pressure limitation restricts the maximum pressure to a set value.

The LSP and LSPT controllers are further developments based on the LSNR and LSNRT controllers. They offer better control behaviour and a two-part dynamic screw for individual adjustment of the on-stroke and destroke velocities.

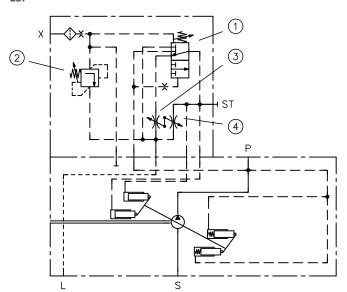
LSP

- Connection X-R sealed
- Standard version for combination with hydraulic valves that relieve the LS signal in the valve, for example proportional directional spool valve type PSV

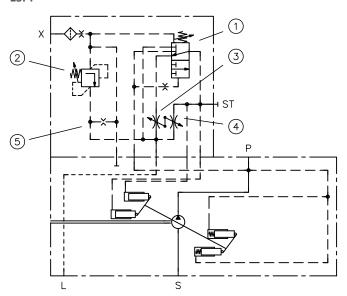
LSPT

- Connection X-R open
- Only for use with hydraulic valves without their own relief of the LS signal





LSPT

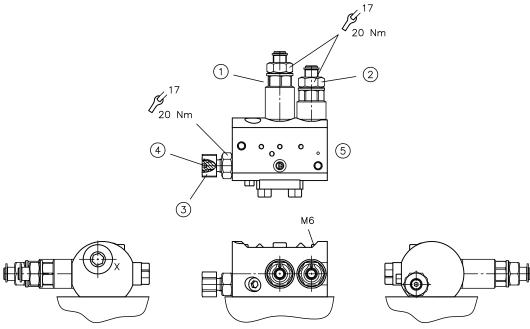


- Flow controller: Regulates a constant difference between load pressure and 1 pump pressure
- 2 Pressure limitation: Limits the pump pressure to a maximum value
- 3 Return throttle
- 4 Bypass throttle

- Flow controller: Regulates a constant difference between load pressure and pump pressure
- 2 Pressure limitation: Limits the pump pressure to a maximum value
- 3 Return throttle
- 4 Bypass throttle
- 5 LS signal relief

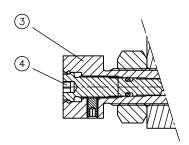


LSP, LSPT



Adjustment range for ① and ② restricted by retaining ring.

- 1 Differential pressure Δp (stand-by pressure)
- 2 Maximum pressure pmax (pressure limitation)
- 3 Return throttle
- 4 Bypass throttle
- 5 X port for LS signal: G 1/4
 Order coding for adapter to 9/16-18 UNF (SAE-6): 7993245.00



- 3 Return throttle
- 4 Bypass throttle

Description of the two-part dynamic screw

- While the pump is swinging out, the return throttle (outer screw on the two-part dynamic screw) adjusts the on-stroke time from V_{gmin} to V_{gmax}.
 - Loosening the screw reduces the damping and accelerates the on-stroke time.
 - Adjustment range: Approx. 5.5 rotations/4 mm
- While the pump is swinging in, a bypass throttle (inner screw on the two-part dynamic screw) adjusts the destroke time from V_{gmax} to V_{gmin}
 - Loosening the screw increases the damping and slows down the destroke time.
 - Tightening the screw reduces the damping and accelerates the destroke time.
 - Adjustment range: Approx. 4 rotations/2 mm

Pressure adjustment	Pressure range (bar)	Δp (bar)/revolution	Factory-set pressure setting (bar)
Maximum pressure p _{max}	20 to 400	approx. 50	300
Differential pressure Δp 20 to 55		approx. 10	27





⚠ CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

2.7.2 Load-sensing controller LSNR, LSNRT



DAMAGE

Discontinued type, for new projects use load-sensing controller LSP, LSPT.

The LSNR, LSNRT controllers are flow controllers that generate a variable, speed-independent flow rate. They adapt the displacement volume of the pump to the required flow rate of the consumer and regulate a constant difference between load pressure and pump pressure.

The integrated pressure limitation restricts the maximum pressure to a set value.

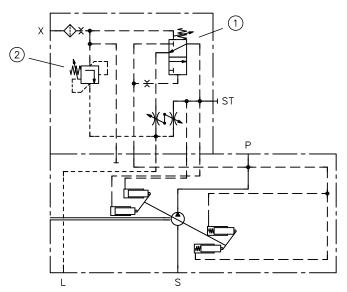
LSNR

- Connection X-R sealed
- Version for combination with hydraulic valves that relieve the LS signal in the valve, for example, type PSV proportional directional spool valve

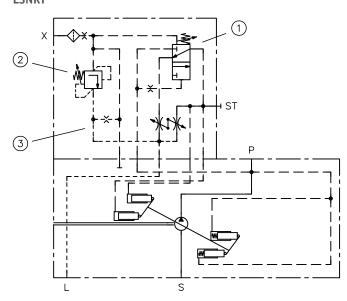
LSNRT

- Connection X-R open
- Only for use with hydraulic valves without their own relief of the LS signal

LSNR



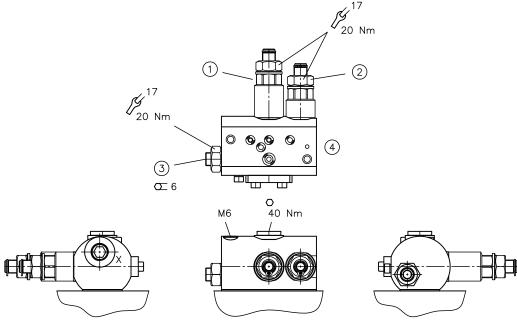
LSNRT



- Flow controller: Regulates a constant difference between load pressure and 1
- Pressure limitation: Limits the pump pressure to a maximum value
- Flow controller: Regulates a constant difference between load pressure and pump pressure
- Pressure limitation: Limits the pump pressure to a maximum value
- Relief of the LS signal (only LSNRT)



LSNR, LSNRT



Adjustment range for ① and ② restricted by retaining ring.

- 1 Differential pressure Δp (stand-by pressure)
- Maximum pressure pmax (pressure limitation) 2
- Dynamic throttle
- X port for LS signal: G 1/4 Order coding for adapter to 9/16-18 UNF (SAE-6): 7993245.00

Pressure adjustment	Pressure range (bar)	Δ p (bar)/revolution	Factory-set pressure setting (bar)
Maximum pressure p _{max}	20 to 400	approx. 50	300
Differential pressure Δ p	20 to 55	approx. 10	27



A CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

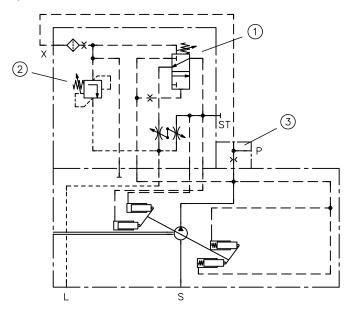


2.7.3 Delivery flow controller QP

The QP controller is a flow controller that generates a constant flow rate independently of the speed. It regulates a constant differential pressure via an orifice in the P channel. The differential pressure is adjustable between 20 and 55 bar. The orifice is available in various graduations (see table).

The integrated pressure limitation restricts the maximum pressure to a set value.

QP



- 1 Flow controller: Regulates a constant differential pressure before and after the orifice
- 2 Pressure limitation: Limits the pump pressure to a maximum value
- 3 Orifice according to table

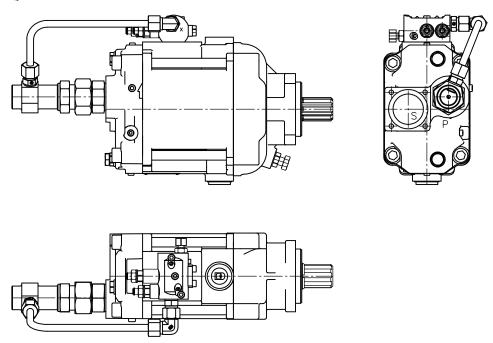
Ordering example:

V60N-110 RDYN-1-0-03/QP/5-350

Orifice (mm)	Flow rate (lpm) at 20 bar differential pressure
3	23
3,5	32
4	42
4,5	53
5	65
5,5	79
6	94
6,5	110
7	127
7,5	146
8	166
8,5	188
9	210
9,5	234
10	260



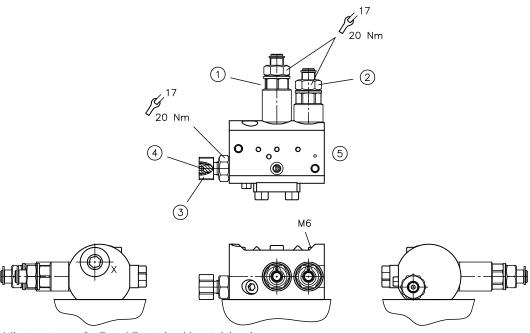
QP



1 NOTE

The hosing varies depending on the size and rotation direction.

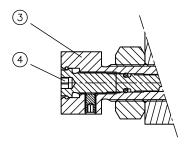
QP



Adjustment range for ① and ② restricted by retaining ring.

- Differential pressure Δp (stand-by pressure)
- Maximum pressure pmax (pressure limitation)
- Return throttle 3
- Bypass throttle
- X port for LS signal: G 1/4 Order coding for adapter to 9/16-18 UNF (SAE-6): 7993245.00





- Return throttle
- Bypass throttle

Description of the two-part dynamic screw

- While the pump is swinging out, the return throttle (outer screw on the two-part dynamic screw) adjusts the on-stroke time from V_{qmin} to V_{qmax} .
 - Loosening the screw reduces the damping and accelerates the on-stroke time.
 - Adjustment range: Approx. 5.5 rotations/4 mm
- While the pump is swinging in, a bypass throttle (inner screw on the two-part dynamic screw) adjusts the destroke time from V_{gmax} to V_{qmin}
 - Loosening the screw increases the damping and slows down the destroke time.
 - Tightening the screw reduces the damping and accelerates the destroke time.
 - Adjustment range: Approx. 4 rotations/2 mm

Pressure adjustment	Pressure range (bar)	Δ p (bar)/revolution	Factory-set pressure setting (bar)
Maximum pressure p _{max}	20 to 400	approx. 50	300
Differential pressure Δp	20 to 55	approx. 10	27



CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

2.7.4 Flow controller ZV, ZV1 and V

The ZV-, ZV1- and V controllers are electro-proportional flow controllers that generate a variable, speed-dependent flow rate. They adjust the displacement volume of the pump based on an electrical input signal. The resulting flow rate depends on displacement volume and rotation speed.

The required pilot pressure for adjusting the swivel angle is tapped internally. When used in open centre systems with operating pressures of < 25 bar, an external auxiliary pump or a pre-load valve must be provided to ensure reliable adjustment.

ZV controller: V60N-060/090/110, increasing characteristic curve Only possible in combination with an NR2 coding pressure controller!

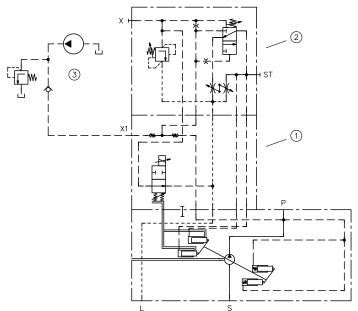
ZV1 controller: V60N-060/090/110, decreasing characteristic curve Only possible in combination with an NR2 coding pressure controller!

V controller: V60N-130, increasing characteristic curve

Only possible in combination with an NR3 coding pressure controller!



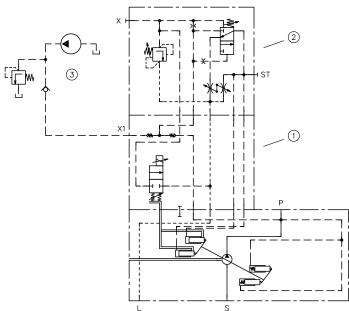
NR2/ZV



- 1 ZV controller
- 2 NR2 controller
- 3 External auxiliary pump, pressure-limiting valve and check valve (not included)

Recommended flow rate: 3-4 lpm Recommended pressure: 40-60 bar

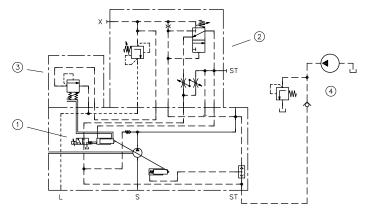
NR2/ZV1



- 1 ZV1 controller
- 2 NR2 controller
- 3 External auxiliary pump, pressure-limiting valve and check valve (not included)

Recommended flow rate: 3-4 lpm Recommended pressure: 40-60 bar

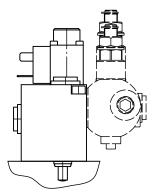
NR3/V/L

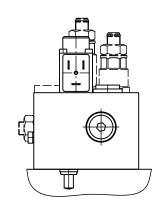


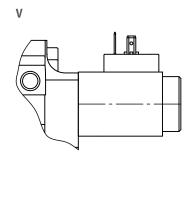
- 1 V controller
- 2 NR3 controller
- 3 L controller (installed as standard for V60N-130)
- 4 External auxiliary pump, pressure-limiting valve and check valve (not included in scope of delivery)



ZV, ZV1Intermediate plate version







2.7.5 Pressure controller NR, NR2, NR3

The NR, NR2, NR3 controllers are pressure controllers with a fixed pressure setting. As soon as the pump pressure exceeds the set value, they reduce the swivel angle of the pump and regulate a constant pressure level. The pressure setting is adjusted using an adjusting screw on the controller, and, in addition, an external pilot valve can be connected to the X port to enable remote adjustment when necessary.

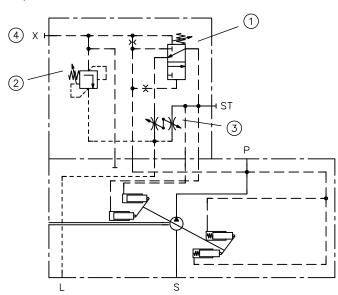
The NR, NR2, NR3 controllers can either be used in constant pressure systems or as a low-loss pressure limitation in combination with an electro-proportional flow controller.

NR controller: Individually or in combination with type ZL and L power controllers

NR2 controller: Only in combination with type ZV and ZV1 flow controllers

NR3 controller: Only in combination with type V flow controllers

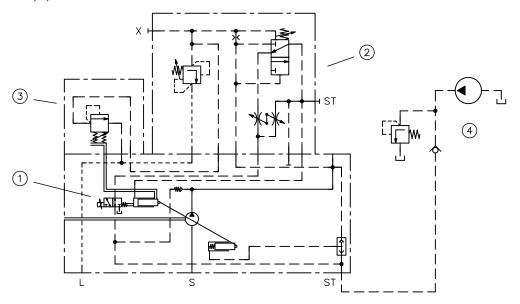
NR, NR2



- 1 Main stage
- 2 pilot valve
- 3 Dynamic throttle
- 4 X port for external pilot valve (optional)

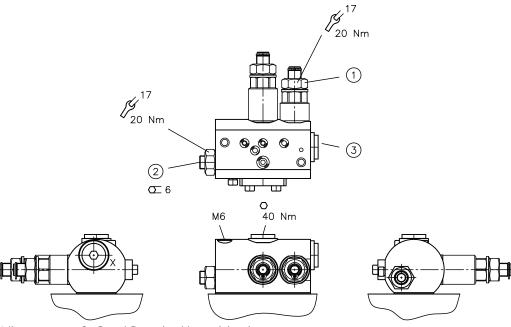


NR3/V/L



- 1 V controller
- 2 NR3 controller
- 3 L controller (installed as standard for V60N-130)
- 4 External auxiliary pump, pressure-limiting valve and check valve (not included in scope of delivery)

NR, NR2, NR3



Adjustment range for ① and ② restricted by retaining ring.

- 1 Maximum pressure pmax
- 2 Dynamic throttle
- 3 X port: G 1/4 Order coding for adapter to 9/16-18 UNF (SAE-6): 7993245.00

Pressure adjustment	Pressure range (bar)	1 \ //	Factory-set pressure setting (bar)
Maximum pressure p _{max}	20 to 400	approx. 50	300



A CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

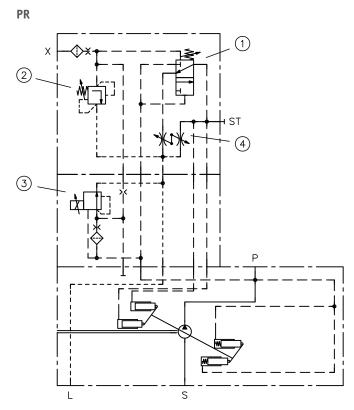
2.7.6 Pressure controller PR, P1R

The PR and P1R controllers are electric proportional pressure controllers. As soon as the pump pressure exceeds the set value, the controller reduces the swivel angle of the pump and regulates a constant pressure level.

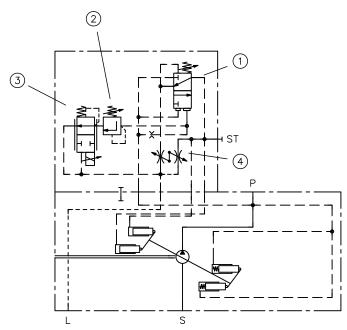
The minimum and maximum pressures are set mechanically on the controller. In between these values, the pressure can be adjusted proportionally using an electrical signal.

PR controller: Increasing characteristic curve, all sizes, cannot be combined with other pump controllers (type ZL or ZV)

P1R controller: Decreasing characteristic curve, only V60N-060/090/110, cannot be combined with other pump controllers (type ZL or ZV)



P1R

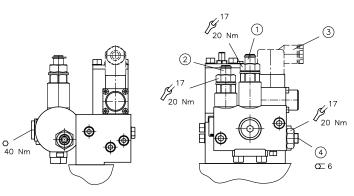


- Maximum pressure setting pmax
- Maximum pressure reduction pred
- Electro-proportional pressure adjustment
- Dynamic throttle

- Minimum pressure setting pmin
- Maximum pressure setting pmax
- Electro-proportional pressure adjustment
- Dynamic throttle

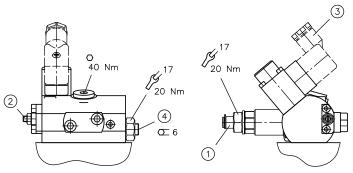


PR



- Minimum pressure pmin
- 2 Maximum pressure pmax
- Electro-proportional pressure adjustment
- Dynamic throttle Adjustment range for 1 and 2 restricted by retaining ring.

P1R



- Maximum pressure pmax
- 2 Maximum pressure reduction pred
- Electro-proportional pressure adjustment
- Dynamic throttle

Pressure adjustment	Pressure range (bar)	Δ p (bar)/revolution	Factory-set pressure setting (bar)
Maximum pressure p _{max} (PR)	20 to 400	approx. 50	300
Maximum pressure p _{max} (P1R)	20 to 400	approx. 140	300
Minimum pressure p _{min}	20 to 55	approx. 10	27



⚠ CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

2.7.7 Power controller ZL and L

The ZL and L controllers are power controllers with fixed settings. As soon as the product of displacement volume and pressure exceeds the set value, the controller reduces the swivel angle of the pump to protect the drive shaft, motor or gearbox from overload ($p_B \times V_q =$ constant).

ZL controller: V60N-060/090/110 L controller: V60N-130 (series)

The setting is made either as a torque limitation (Nm) or power limitation (kW) at the corresponding speed (rpm).

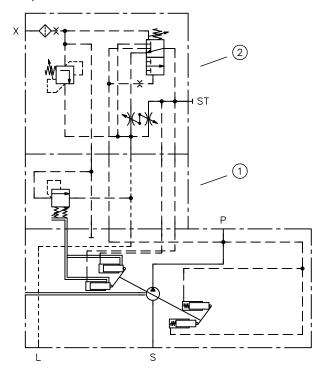
Drive torque $M = \frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_{mh}} (Nm)$

 $P = \frac{2\pi \cdot M \cdot n}{60000} = \frac{Q \cdot \Delta p}{600 \cdot \eta_t} (kW)$ Drive power

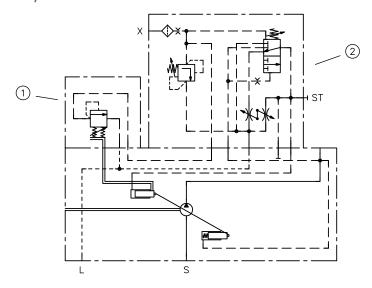
= Geometric output volume (cm³/rev) Δp = Differential pressure = Speed (rpm) = Volumetric efficiency η_{mh} = Mechanical-hydraulic efficiency = Overall efficiency $\eta_T = \eta_V * \eta_{mh}$) Q = Flow rate (lpm) = Torque (Nm) = Power (kW)



LSP/ZL



LSP/L

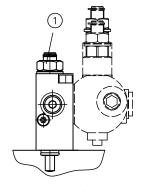


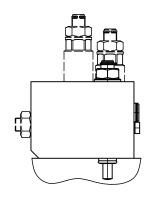
- 1 L controller
- 2 LSP controller

- 1 ZL controller
- 2 LSP controller

ZL

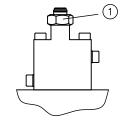
Intermediate plate version







L



Torque setting

I Torque setting

Torque setting

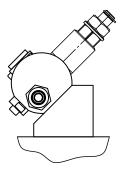
	Δ M (Nm)/revolution	Factory-set torque setting (Nm)	Adjustment range
Power controller ZL	approx. 190	200	25 to 100% of Nm _{max}
Power controller L	approx. 190	700	200 to 700 Nm



2.7.8 ZW intermediate plate

The ZW intermediate plate is a 45° spacer plate. For V60N-060/090/110, it is required for housing versions with radial connections (coding 2 and 3) to avoid a collision between the pump controller and the suction or pressure line.

/ZW



2.8 Stroke limitation

Coding	Description
2	Stroke limitation adjustable (for housing version 1 and 4: all sizes; for housing version 2 and 3: only V60N-090, V60N-130)
2/	Stroke limitation fixed with specification of the set displacement volume Vg (cm³/rev)

2.9 Thread type

Coding	Connections
Without coding	DIN EN ISO 228-1
UNF	SAE J 514



2.10 Flange version (output side)

Ordering example:

V60N-110 RDYN-2-0-01/LSP-350-A00/76- C 022

Coding V60N			Flange	Shaft
060	090/110	130		
C 001	C 002	C 003	Prepared for thru-shaft, sealed with cap	
C 010		C 030	DIN ISO 7653	DIN ISO 14
C 011	C 021	C 031	SAE-A 2-hole J 744 82-2 DIN ISO 3019-1	SAE-A J 744 (16-4 DIN ISO 3019-1) 9T 16/32 DP
C 012	C 022	C 032	SAE-A 2-hole J 744 82-2 DIN ISO 3019-1	SAE-A J 744 (16-4 DIN ISO 3019-1) ¹⁾ 9T 16/32 DP ¹⁾
C 013			SAE-A 2-hole J 744 82-2 DIN ISO 3019-1	19-4 DIN ISO 3019-1 11T 16/32 DP
C 014	C 024	C 034	SAE-B 2-hole J 744 101-2 DIN ISO 3019-1	SAE-B J 744 (22-4 DIN ISO 3019-1) 13T 16/32 DP
	C 026	C 036	SAE-B 2-hole J 744 101-2 DIN ISO 3019-1	SAE-BB J 744 (25-4 DIN ISO 3019-1) 15T 16/32 DP
C 015	C 025	C 035	SAE-B 4-hole J 744 101-4 DIN ISO 3019-1	SAE-B J 744 (22-4 DIN ISO 3019-1) 13T 16/32 DP
	C 027	C 037	SAE-C 2-hole J 744 127-2 DIN ISO 3019-1	SAE-C J 744 (32-4 DIN ISO 3019-1) 14T 12/24 DP
	C 028	C 038	SAE-C 4-hole J 744 127-4 DIN ISO 3019-1	SAE-C J 744 (32-4 DIN ISO 3019-1) 14T 12/24 DP
	C 125	C 135	SAE-B 4-hole J 744 101-4 DIN ISO 3019-1	SAE-BB J 744 (25-4 DIN ISO 3019-1) 15T 16/32 DP

¹⁾ ANSI B 92.1, FLAT ROOT SIDE FIT spline width deviating from the standard, s = 2.357-0.03



DAMAGE

Pay attention to the maximum permissible weight torque and drive torque, as the flange or shaft may be damaged otherwise.



DAMAGE

- An additional support is to be provided for pump combinations.
- Additional versions on request.

2.11 Solenoid voltage and connector

Coding	Electrical connection	Nominal voltage	Protection class (IEC 60529)	PR controller	ZV, ZV1, V, P1R controller
G 12 G 24	DIN EN 175 301-803A	12 V DC 24 V DC	IP 65	•	•
AMP 12 APM 24	AMP Junior Timer	12 V DC 24 V DC	IP 65		•
DT 12 DT 24	German (DT 04-2P)	12 V DC 24 V DC	IP 67		•



3

Parameters

3.1 General data

Designation	Variable displacement axial piston pump						
Design	Axial piston pump according to the swash plate principle						
Mounting	Mounting flange according to DIN ISO 7652, DIN ISO 3019-1 or DIN ISO 3019-2						
Surface	primed RAL 7043	primed RAL 7043					
Drive/output torque	max. permissible drive/output torque (Nm)						
		Nominal size					
		060	090/110	130	-		
	Parallel key splined shaft D	530/100	800/600	800/700	-		
	Spline shaft M		530/530				
	Spline shaft H	210/100					
	Spline shaft U	210/100					
	Spline shaft T	340/100					
	Spline shaft S	530/100	640/600	640/640			
	Spline shaft Q		900/600	900/700			
Installation position	any Installation information see Chapter 5, "Installation, operation and maintenance information"						
Rotation direction	Clockwise or anticlockwise						
Change of rotating direction	V60N-060/-090/-110: Turn the end plate of the pump (see dimension diagram) and replace the port plate; see also Assembly instructions for variable displacement axial piston pump type V60N: B 7960 N						
Ports/connections	 Suction port Pressure connection Drain port Pressure gauge connection LS port 						
Hydraulic fluid	Hydraulic fluid, according to DIN 51 524 Parts 1 to 3; ISO VG 10 to 68 according to DIN ISO 3448 Viscosity range: 10 - 1000 mm²/s Optimal operating range: approx. 16 - 60 mm²/s see restrictions during cold-start and warm-up phase Also suitable for biologically degradable hydraulic fluids type HEPG (polyalkylene glycol) and HEES (synthetic ester) at operating temperatures up to approx. +70°C.						
Cleanliness level	ISO 4406 19/17/14						



Temperatures

Environment: approx. -40 to +60 °C, hydraulic fluid: -25 to +80 °C, pay attention to the viscosity range. Start temperature: down to -40 °C is permissible (take account of the start viscosities!), as long as the steady-state temperature is at least 20 K higher during subsequent operation. Biologically degradable hydraulic fluids: note manufacturer specifications. With consideration for the seal compatibility, not above +70°C.

Designation		Nominal size			
		060	090	110	130
Max. swash plate angle		20.5°	21.5°	21.5°	21.5°
Absolute inlet pressure required in open circuit	bar	0.85	0.85	0.85	0.85
Max. permissible housing pressure (static/dynamic)	bar	2/3	2/3	2/3	2/3
Max. permissible inlet pressure (static/dynamic)	bar	20/30	20/30	20/30	20/30
Max. speed during suction operation and max. swash plate angle at 1 bar abs. Inlet pressure	rpm	2500	2300	2200	2100
Max. speed with zero stroke and 1 bar abs. Inlet pressure	rpm	3000	3000	3000	3000
Min. speed in continuous operation	rpm	500	500	500	500
Required drive torque at 100 bar	Nm	100	151	184	230
Drive power at 250 bar and 2000 rpm	kW	53	79.5	97.2	120
Weight torque	Nm	30	35,5	40	40
Inertia torque	kg m ²	0.005	0.008	0,01	0,011
Noise level at 250 bar, 1500 rpm and max. swash plate angle (measured in acoustic measurement chamber according to DIN ISO 4412-1, measuring distance 1 m)	dB(A)	75	75	75	75



DAMAGE

The minimum operating pressure in the pump line depends on the speed and the swivel angle; the pressure must not fall below 15 bar under any circumstances.



DAMAGE

The housing pressure is only allowed to be 1 bar higher than the suction pressure.

3.2 Weight

Туре	Without controller (kg)	With controller (kg)					
		LSP, LSPT, LSNR, LSNRT, NR, NR2, NR3	ZL	ZW	PR	P1R	ZV, ZV1
V60N-060	23	+ 1.0	+ 1.0	+ 0.7	+ 2.3	+ 1.2	+ 1.9
V60N-090	26	+ 1.0	+ 1.0	+ 0.7	+ 2.3	+ 1.2	+ 1.9
V60N-110	29	+ 1.0	+ 1.0	+ 0.7	+ 2.3	+ 1.2	+ 1.9
V60N-130	29,8	+ 1.0	+ 1.0		+ 2.3		



3.3 Pressure and delivery flow

Operating pressure	see Chapter 2.1, "Basic type and nominal size"
displacement volume	see Chapter 2.1, "Basic type and nominal size"

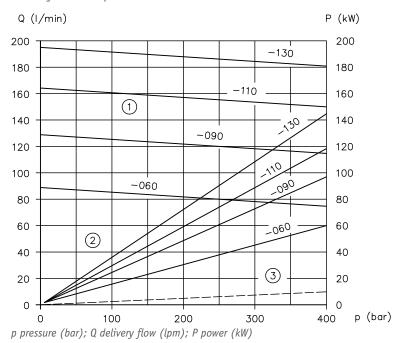
3.4 Characteristic lines

3.4.1 Basic pump

Delivery flow and power

The diagram shows delivery flow and drive power over pressure without a controller at 1500 rpm.

Delivery flow and power



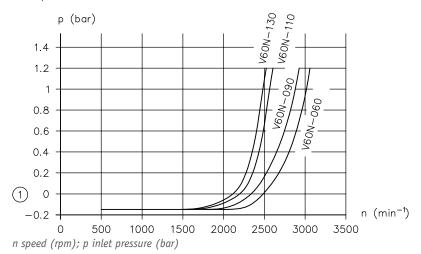
- 1 Delivery flow/pressure
- 2 Drive power/pressure (max. swash plate angle)
- 3 Drive power/pressure (zero stroke)



Inlet pressure and self-suction speed

The diagram shows the inlet pressure/speed at max. swash plate angle and oil viscosity of 75 mm²/s.

Inlet pressure



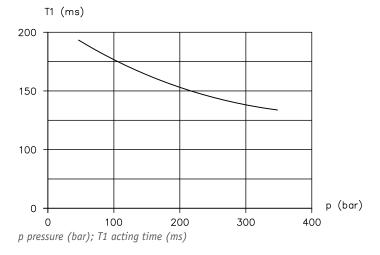
1 0 bar relative = 1 bar absolute

Acting times

Acting times T1 (LSP and LSPT controllers)

The diagram illustrates the on-stroke time based on the pressure for the LSP and LSPT controllers, i.e. the time required to swing out the pump and to adjust the displacement volume from the minimum to the maximum.

Acting time T1 (LSNR controller)

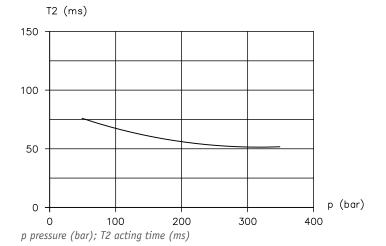


Acting times T2 (LSP and LSPT controllers)

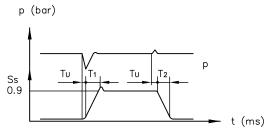
The diagram shows the destroke time based on the pressure for the LSP and LSPT controllers, i.e. the time required to swing in the pump and to adjust the displacement volume from the maximum to the minimum.



Acting time T2 (LSNR controller)



Acting times Tu, T1 and T2



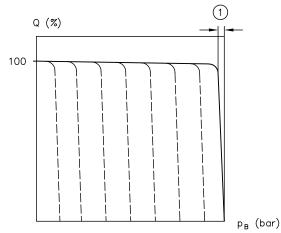
t acting times (ms); p pressure (bar)

- SS Positioning travel of actuator
- Tu Delay < 3 ms
- T1 On-stroke time
- T2 Destroke time
- p Pressure

3.4.2 Controllers

Load-sensing controller LSP, LSPT, LSNR, LSNRT

LSP, LSPT

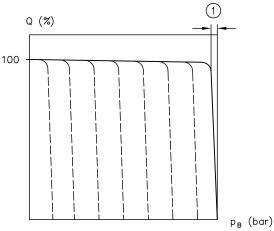


pB operating pressure (bar); Q delivery flow (%)

1 Approx. 4 bar



LSNR, LSNRT

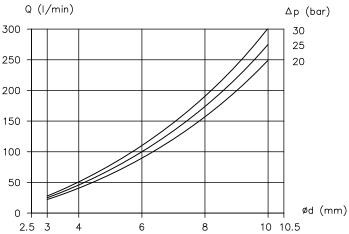


pB operating pressure (bar); Q delivery flow (%)

1 Approx. 4 bar

Flow controller QP, ZV, ZV1, V

QP



 \varnothing d orifice diameter (mm); Q delivery flow (lpm); Δp pressure difference (bar)

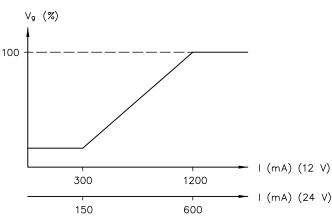
Determination of the flow rate

$$Q = 0,55 \cdot d^2 \sqrt{\Delta p}$$

$$\Delta p$$
 = Pressure difference (bar)

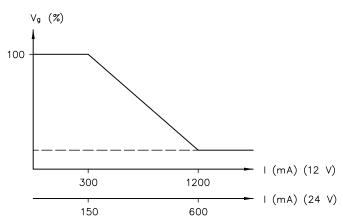


Z۷



I current (mA); Vq displacement volume (%)

ZV1



I current (mA); Vq displacement volume (%)

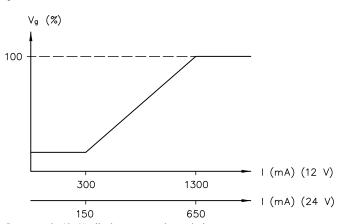


1 NOTE

 $V_g = 0 \text{ cm}^3/\text{rev}$ possible through the use of an auxiliary pump.

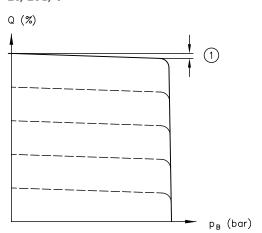
At $V_q = 0$ cm³/rev, additional rinsing via the drain port is required to ensure sufficient lubrication of the pump. Recommended flow rate: 3 lpm.

٧



I current (mA); Vg displacement volume (%)

ZV, ZV1, V



pB operating pressure (bar); Q delivery flow (%)

Approx. 5%



1 NOTE

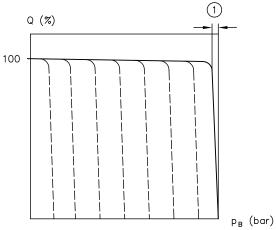
 $V_q = 0$ cm³/rev possible through the use of an auxiliary pump.

At $V_q = 0$ cm³/rev, additional rinsing via the drain port is required to ensure sufficient lubrication of the pump. Recommended flow rate: 3 lpm.



Pressure controller NR, NR2, NR3, PR, P1R

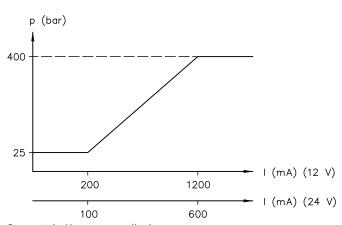
Characteristic curves NR, NR2, NR3



pB operating pressure (bar); Q delivery flow (%)

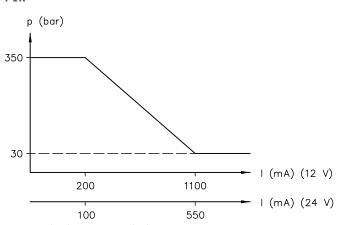
1 Approx. 4 bar

PR



I current (mA); p pressure (bar)

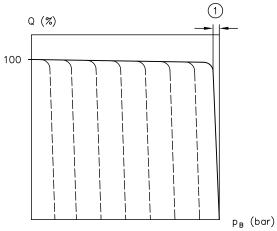




I current (mA); p pressure (bar)



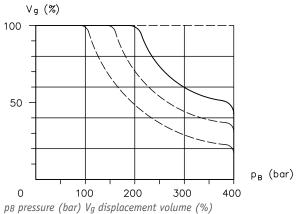
PR, P1R



pB operating pressure (bar); Q delivery flow (%)

1 Approx. 4 bar

Power controller ZL, L





3.5 Electrical data

Controller coding ZV, ZV1, PR, P1R

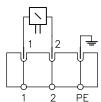
Nominal voltage	12 VDC	24 VDC		
Resistance R ₂₀	5.9 Ω	24 Ω		
Current, cold I ₂₀	2.0 A	1.0 A		
Limit current IG	1.26 A	0.63 A		
Limit power PG	14.1 W	14.1 W		
Duty cycle	S1 (100 %)			
Dither frequency	210 Hz			
Dither amplitude	0 % ≤ A	_D ≤ 20 %		
$A_D(\%) = \frac{I_{\text{Peak-Peak}}}{IG} \cdot 100$				

Controller coding V

Nominal voltage	12 VDC	24 VDC		
Resistance R ₂₀	7 Ω	24 Ω		
Current, cold I ₂₀	1.7 A	1.0 A		
Limit current I _G	1.3 A	0.7 A		
Limit power PG	17.7 W	17.8 W		
Duty cycle	S1 (100 %)			
Dither frequency	60 - 110 Hz			
Dither amplitude	20 % ≤ A _D ≤ 40 %			
$A_D(\%) = \frac{I_{\text{Peak-Peak}}}{IG} \cdot 100$				

Electrical connection

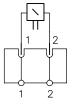
G 12, G 24



G .., X .., L .. (WG ..)



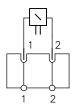
AMP 12, AMP 24



AMP ..



DT 12, DT 24



DT ..





4

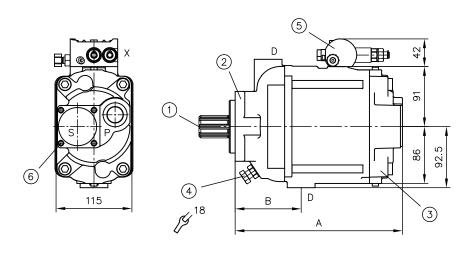
Dimensions

All dimensions in mm, subject to change.

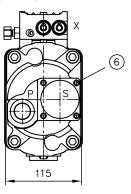
4.1 Basic pump

4.1.1 Type V60N-060

Rotation direction clockwise (viewed from shaft journal)



Rotation direction **anti-clockwise** (viewed from shaft journal)



- 1 Shaft journal
- 2 Flange version Y
- 3 Thru-shaft
- 4 Stroke limitation (13 cm³/rev.)
- Controller and intermediate plate see Chapter 4.2, "Controllers and intermediate plates"
- 6 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Flange version	Thru-shaft	Α	В
Υ	-1	253,5	100,0
F, Z, X	-1	249,8	96,3
Υ	-2, -3	292,0	100,0
F, Z, X	-2, -3	288,3	96,3

Ports P, S and D (ISO 228-1)

For coding UNF, ports SAE J 514

Р	Pressure port G 3/4	Р	Pressure connection 1 1/16-12 UN-2B
S	Flange suction port	S	Flange suction port
D	Drain port G 3/4	D	Drain port 1 1/16-12 UN-2B
Χ	G 1/4	Χ	G 1/4 (ISO 228-1) with adapter to 7/16-20 (SAE-4)



Shaft journal

Parallel key splined

shaft

Coding S

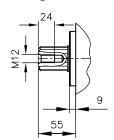
Spline shaft



Spline shaft

Spline shaft

Coding **D**



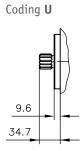
12.7

56.1

Coding **T** 9.6 46

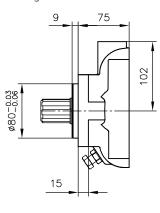
Coding H 9.6

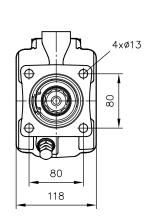
41.2



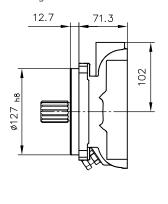
Flange version (input side)

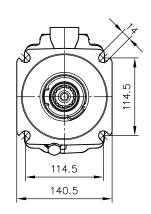
Coding Y





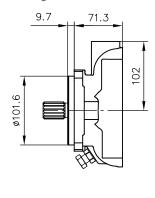
Coding **F**

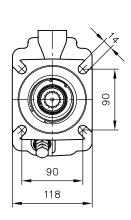




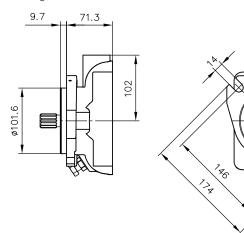
Bleeding G 1/8

Coding **Z**





Coding X



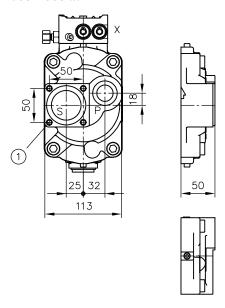
Bleeding G 1/8



Thru-shaft

Housing version (axial ports)

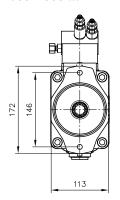
V60N-060 ...-1

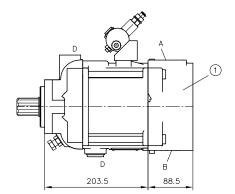


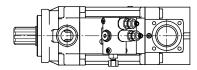
1 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Housing version (radial ports, with thru-shaft)

V60N-060 ...-2







Rotation direction clockwise

A = suction port

Rotation direction anti-clockwise

A = pressure connection

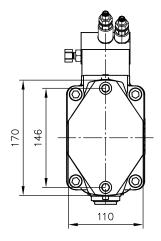
Flange version (output side)

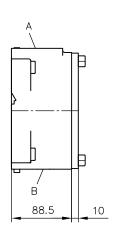
B = pressure connection B = suction port

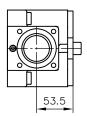


Housing version (radial ports)

V60N-060 ...-3



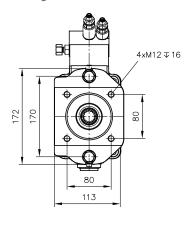


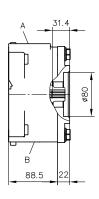


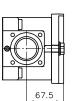
Rotation direction clockwise	Rotation direction anti- clockwise
A = suction port	A = pressure connection
B = pressure connection	B = suction port

Flange version (output side)

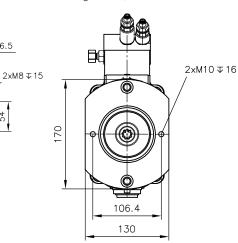
Coding C 010

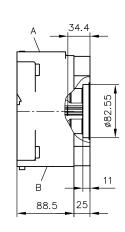


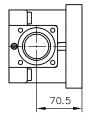




Coding C 011, C 012



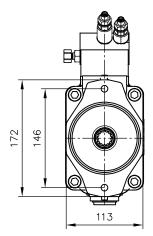


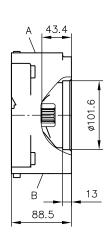


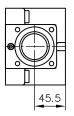
16.5



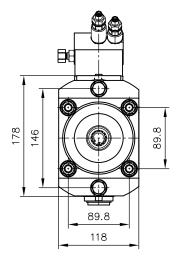
Coding C 014

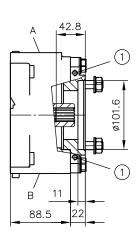


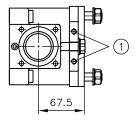




Coding C 015







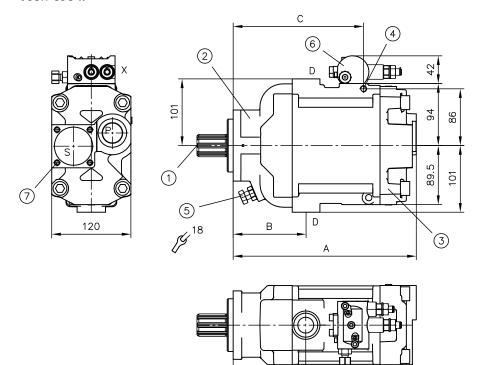
1 Support 8xM8



4.1.2 Type V60N-090

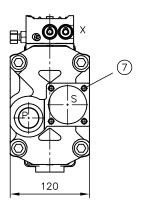
Rotation direction **clockwise** (viewed from shaft journal)

V60N-090 R



Rotation direction **anti-clockwise** (viewed from shaft journal)

V60N-090 L



- 1 Shaft journal
- 2 Flange version
- 3 Thru-shaft
- 4 Thread M10 for attaching a support
- 5 Stroke limitation (13 cm³/rev.)
- 6 Controller and intermediate plates see Chapter 4.2, "Controllers and intermediate plates"

В

7 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Flange version	Thru-shaft	Α	В	С
Υ	-1	277,5	110,0	198,0
F, G	-1	273,8	106,3	194,3
Υ	-2, -3	310,5	110,0	198,0
F, G	-2, -3	306,8	106,3	194,3

Ports P, S and D (ISO 228-1)

For coding UNF, ports SAE J 514

Р	Pressure port G 1	P	Pressure port 1 5/16-12 UN-2B
S	Flange suction port	S	Flange suction port
D	Drain port G 3/4	D	Drain port 1 1/16-12 UN-2B
Χ	G 1/4	Χ	G 1/4 (ISO 228-1) with adapter to 7/16-20 (SAE-4)



Shaft journal

Parallel key splined

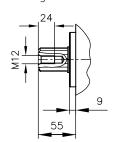
shaft

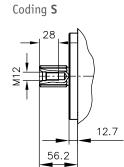
Spline shaft

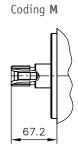
Spline shaft

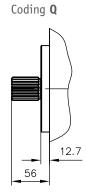
Spline shaft

Coding **D**



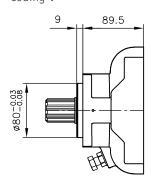


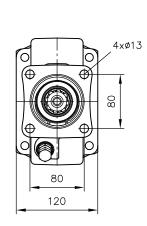


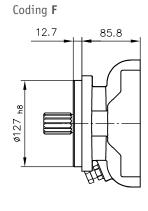


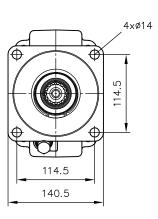
Flange versions (input side)

Coding Y

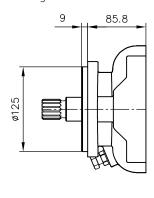


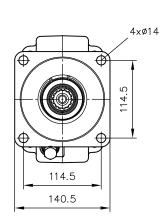






Coding ${\bf G}$



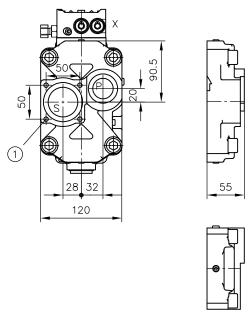




Thru-shaft

Housing version (axial ports)

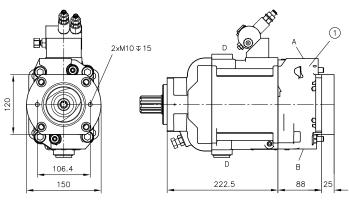
V60N-090 ...-1

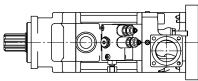


1 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Housing version (radial ports, with thru-shaft)

V60N-090 ...-2





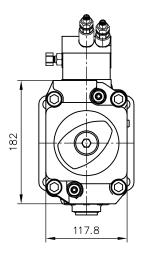
1 Flange version (output side)

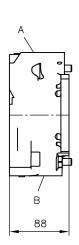
Rotation direction clockwise	Rotation direction anti- clockwise
A = suction port	A = pressure connection
B = pressure connection	B = suction port

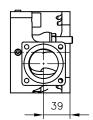


Housing version (radial ports)

V60N-090 ...-3



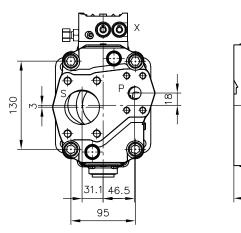


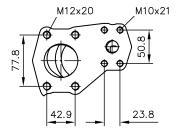


Rotation direction anticlockwise A = suction port B = pressure connection B = suction port B = suction port

Housing version (axial ports, ports SAE J 518)

V60N-090 ...-4





55

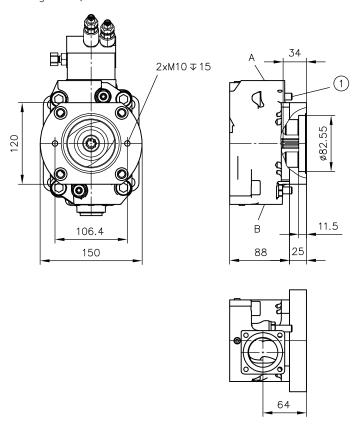
Connections (SAE J 518)

Р	Pressure connection SAE 3/4"	(6000 psi)
S	Suction port SAE 2"	(3000 psi)



Flange versions (output side)

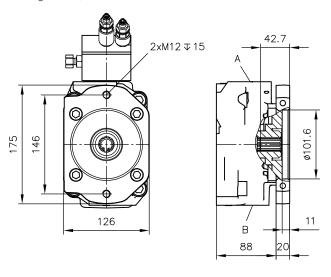
Coding **C 021, C 022**



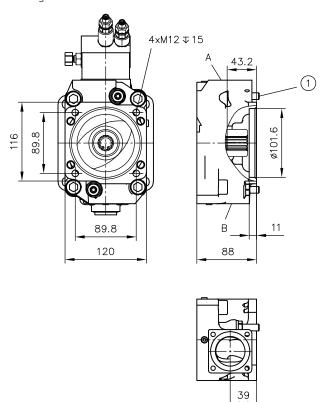
1 Stroke limitation



Coding C 024, C 026



Coding C 025

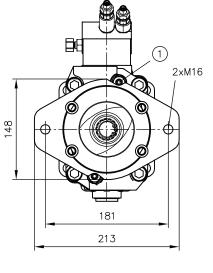


1 Stroke limitation

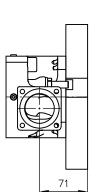
59



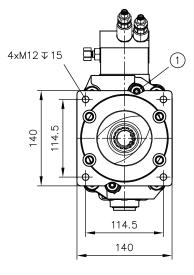
Coding C 027

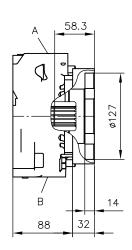


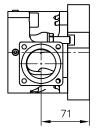
A 58.3 A 2218 B 14 88 32



Coding C 028







Stroke limitation

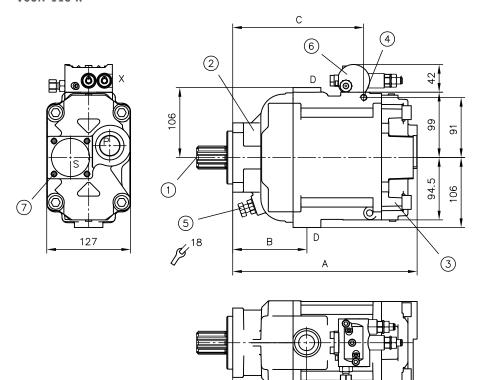
1 Stroke limitation



4.1.3 Type V60N-110

Rotation direction **clockwise** (viewed from shaft journal)

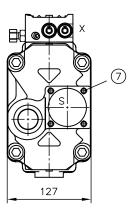
V60N-110 R



В

Rotation direction **anti-clockwise** (viewed from shaft journal)

V60N-110 L



- 1 Shaft journal
- 2 Flange version
- 3 Thru-shaft
- 4 Thread M10 for attaching a support
- 5 Stroke limitation (13 cm³/rev.)
- 6 Controller and intermediate plates see Chapter 4.2, "Controllers and intermediate plates"
- 7 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Flange version	Thru-shaft	Α	В	С
Υ	-1	279,5	112,0	201,0
F	-1	275,7	108,7	197,7
P	-1	278,5	111,0	200,0
Υ	-2, -3	313,5	112,0	201,0
F	-2, -3	309,7	108,2	197,7
P	-2, -3	312,5	111,0	200,0

Ports P, S and D (ISO 228-1)

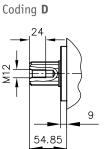
For coding UNF, ports SAE J 514

Р	Pressure port G 1	Р	Pressure port 1 5/16-12 UN-2B
S	Flange suction port	S	Flange suction port
D	Drain port G 3/4	D	Drain port 1 1/16-12 UN-2B
Χ	G 1/4	X	G 1/4 (ISO 228-1) with adapter to 7/16-20 (SAE-4)



Shaft journal





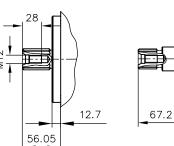
Spline shaft

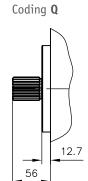
Coding S

Spline shaft

Spline shaft

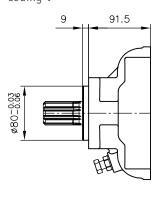
Coding M

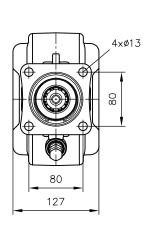


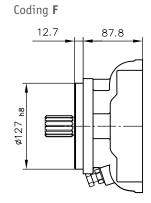


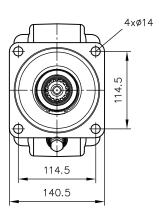
Flange version (input side)

Coding Y

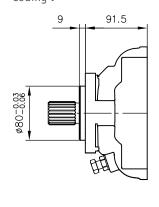


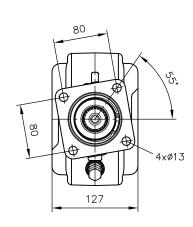


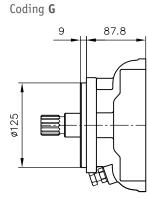


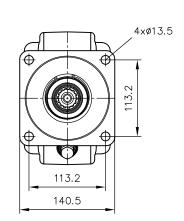


Coding P







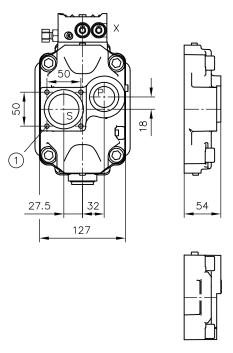




Thru-shaft

Housing version (axial ports)

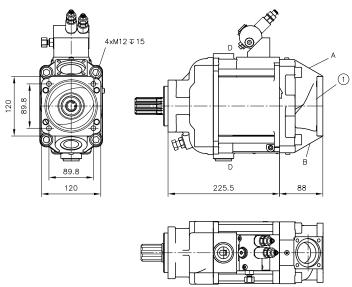
V60N-110 ...-1



1 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Housing version (radial ports with thru-shaft)

V60N-110 ...-2



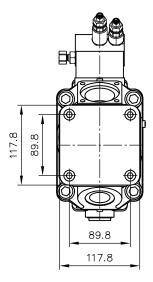
1	Elango	version	(autnut	cida)
Τ.	rialiue	version	toutbut	sidel

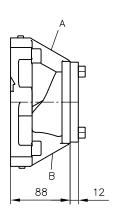
Rotation direction clockwise	Rotation direction anti- clockwise
A = suction port	A = pressure connection
B = pressure connection	B = suction port



Housing version (radial ports)

V60N-110 ...-3



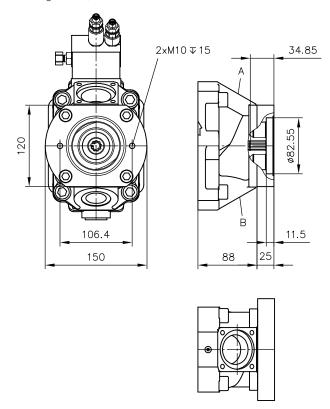




Rotation direction clockwise	Rotation direction anti- clockwise
A = suction port	A = pressure connection
B = pressure connection	B = suction port

Flange version (output side)

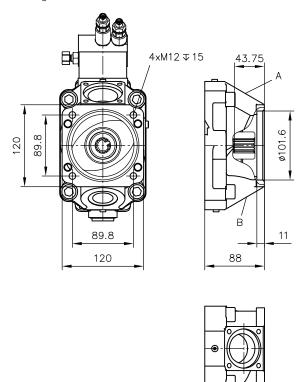
Coding C 021, C 022



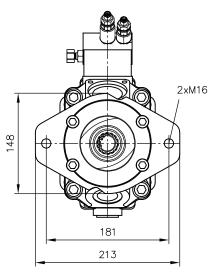


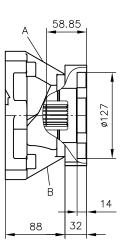
Coding C 024, C 026

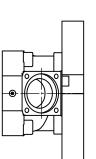
Coding C 025



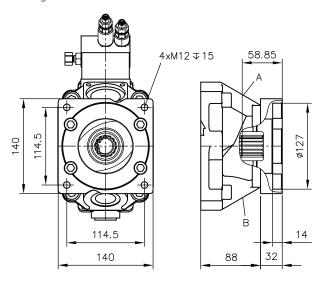
Coding C 027

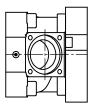






Coding C 028



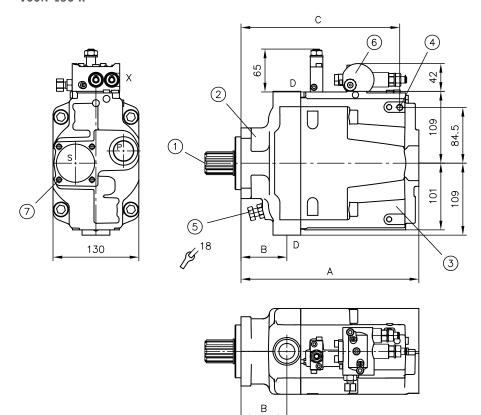




4.1.4 Type V60N-130

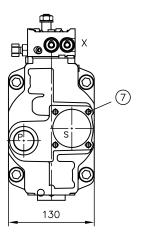
Rotation direction **clockwise** (viewed from shaft journal)

V60N-130 R



Rotation direction **anti-clockwise** (viewed from shaft journal)

V60N-130 L



- 1 Shaft journal
- 2 Flange version
- 3 Thru-shaft
- 4 Thread M10 for attaching a support
- 5 Stroke limitation (13 cm³/rev.)
- 6 Controller and intermediate plates see Chapter 4.2, "Controllers and intermediate plates"
- 7 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

Flange version	Thru-shaft	Α	В	С
Y, P	-1	269,5	69,5	240,5
F	-1	266,8	66,8	237,8
Y, P	-2	323,5	69,5	240,5
F	-2	320,8	66,8	237,8

Ports P, S and D (ISO 228-1)

For coding UNF, ports SAE J 514

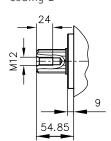
Р	Pressure port G 1	Р	Pressure port 1 5/16-12 UN-2B
S	Flange suction port	S	Flange suction port
D	Drain port G 3/4	D	Drain port 1 1/16-12 UN-2B
Χ	G 1/4	Χ	G 1/4 (ISO 228-1) with adapter to 7/16-20 (SAE-4)



Shaft journal

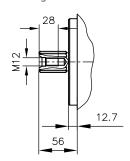
Spline shaft

Coding **D**



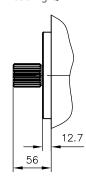
Spline shaft

Coding S



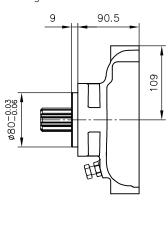
Spline shaft

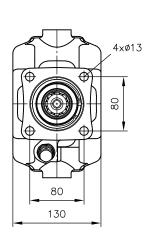
Coding Q



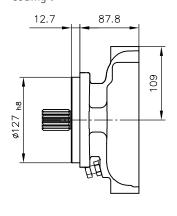
Flange version (input side)

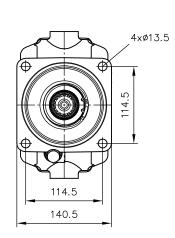
Coding Y



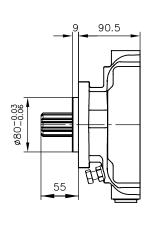


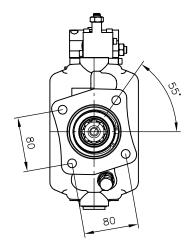
Coding **F**





Coding P



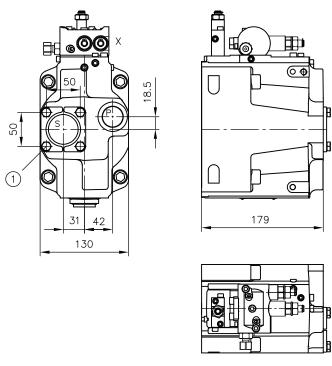




Thru-shaft

Housing version (axial ports)

V60N-130 ...-1

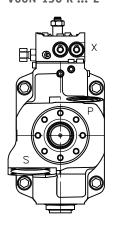


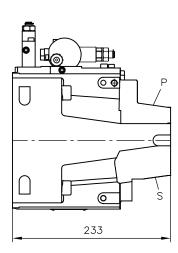
1 Attachment kit for suction intake see Chapter 6.1.1, "Suction intake" (included)

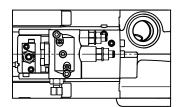
Housing version (radial ports, with thru-shaft)

Rotation direction clockwise

V60N-130 R ...-2

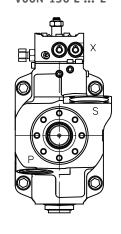


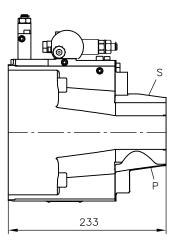


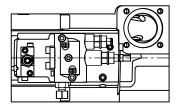


Rotation direction anti-clockwise

V60N-130 L ...-2



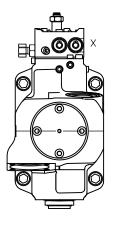


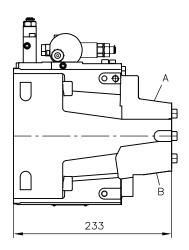


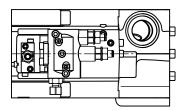


Housing version (radial ports)

V60N-130 ...-3



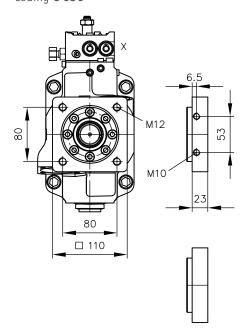




Rotation direction clockwise	Rotation direction anti- clockwise				
A = pressure connection	A = suction port				
B = suction port	B = pressure connection				

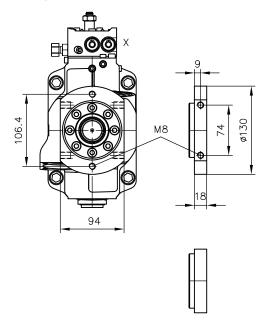
Flange version (output side)

Coding C 030

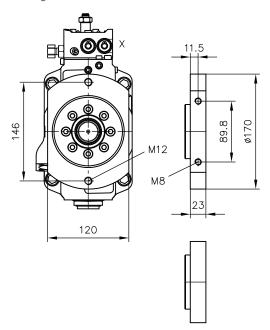




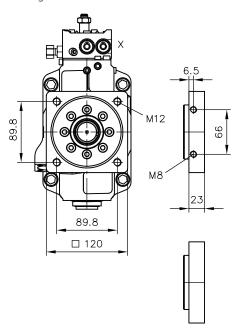
Coding C 031



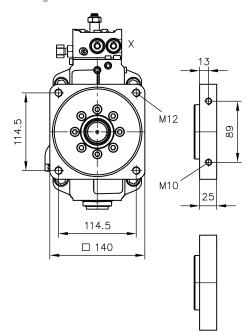
Coding C 034



Coding C 035



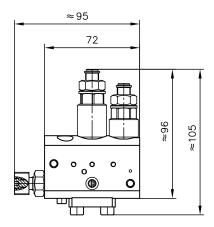
Coding C 038

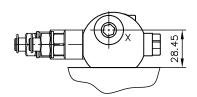


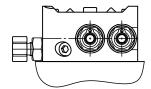


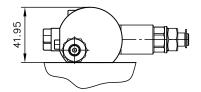
4.2 Controllers and intermediate plates

Coding LSP, LSPT

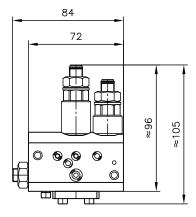


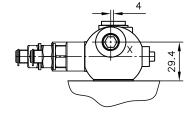


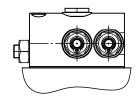


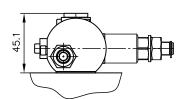


Coding LSNR, LSNRT



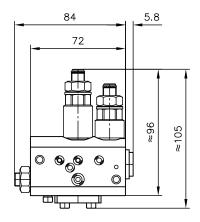


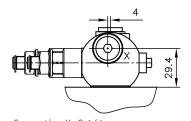


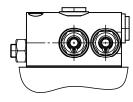


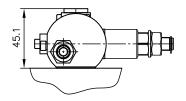


Coding NR



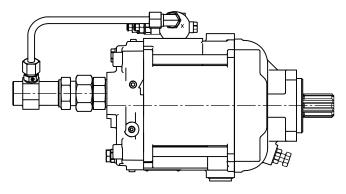


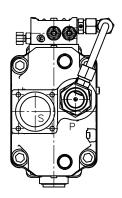


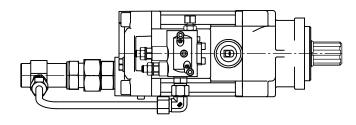


Connection X: G 1/4 LS signal port order coding for adapter for UNF thread 79 93245 00

Coding QP







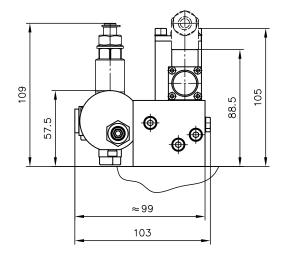


NOTE

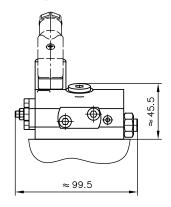
The piping varies depending on the size and rotation direction.

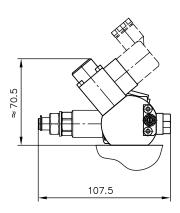


Coding PR

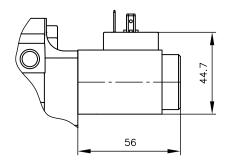


Coding P1R

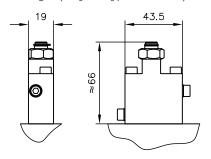




Coding V

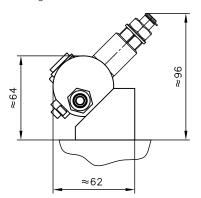


Coding L (only for type V60N-130)



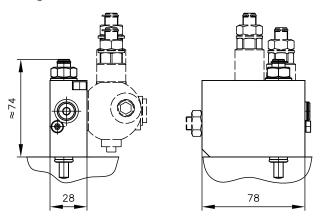
Intermediate plates

Coding **ZW**

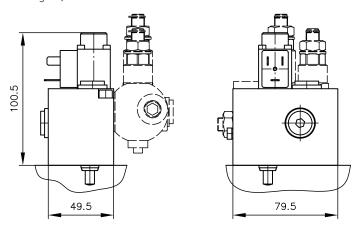




Coding **ZL**



Coding ZV, ZV1





CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.



Installation, operation and maintenance information

Observe the document B 5488 "General operating instructions for assembly, commissioning, and maintenance."

5.1 Intended use

This product is intended exclusively for hydraulic applications (fluid technology).

The user must observe the safety measures and warnings in this document.

Essential requirements for the product to function correctly and safely:

- All information in this documentation must be observed. This applies in particular to all safety measures and warnings.
- ► The product must only be assembled and put into operation by specialist personnel.
- The product must only be operated within the specified technical parameters described in detail in this document.
- All components must be suitable for the operating conditions when using an assembly.
- The operating instructions for the components, assemblies and the specific complete system must also always be observed.

If the product can no longer be operated safely:

- 1. Remove the product from operation and mark it accordingly.
 - ✓ It is then not permitted to continue using or operating the product.

5.2 Assembly information

The product must only be installed in the complete system with standard and compliant connection components (screw fittings, hoses, pipes, fixtures etc.).

The product must be shut down correctly prior to disassembly (in particular in combination with hydraulic accumulators).



DANGER

Sudden movement of the hydraulic drives when disassembled incorrectly

Risk of serious injury or death

- ► Depressurise the hydraulic system.
- ► Perform safety measures in preparation for maintenance.

5.2.1 General information

The variable displacement axial piston pump is suitable for use in an open or semi-closed circuit.

The pump can be flange-mounted on the usual mounting points (e.g. gearbox power take-off, combustion engine or electric drive, cardan shaft) using a flange mounting. Suitable coupling flanges are available as accessories for attachment to a cardan shaft "coupling flanges for cardan shafts".

In order to reduce the weight torque of the pump, a separate support can be attached in addition to the flange mounting. For this purpose, M10 threads are included in the pump housing (only V60N-090/110/130)see Chapter 4, "Dimensions" A change of rotating direction is available for types V60N-060, V60N-090 and V60N-110 variable displacement axial piston pumps. For conversion instructions, please get in touch with HAWE Hydraulik SE. The housing pressure in the pump must always be greater than or equal to the ambient pressure.

During assembly, note the following principles:

- Only trained persons are allowed to mount or remove the pump.
- Always ensure absolute cleanliness to prevent contamination from affecting the pump.
- Remove all plastic plugs before operation.
- Avoid installation above the tank (see Chapter 5.2.3, "Installation positions").
- Observe the electric reference values.



- Before initial use, fill the pump with hydraulic fluid and bleed. Automatic pump filling via the suction line by opening the drain ports
 is not possible.
- Always supply the pump with hydraulic fluid from the start. Even just a short period with insufficient hydraulic fluid can damage the pump. Such damage is not immediately visible once the pump is put into operation.
- Never drain the pump.
- Hydraulic fluid which flows back into the tank must not be sucked back in immediately (install baffles!).
- If there is a check valve installed in the leakage line, negative pressure may occur in the pump housing during operation. If this happens, install an auxiliary pump to flush the housing.
- Before first use, run the pump for approx. 10 minutes at max. 50 bar after initial start-up.
- The leakage line must be installed in the tank in such a way that it ends below the oil level. The end of the leakage line should be positioned roughly equidistant from both the bottom of the tank and the oil level.
- Do not use the entire pressure range of the pump until it has been thoroughly bled and flushed.
- From the start, always keep the temperature within the specified range (see Chapter 3, "Parameters"). Never exceed the maximum temperature.
- Always comply with the cleanliness level of the hydraulic fluid. In addition, filter the hydraulic fluid appropriately (see Chapter 3, "Parameters").
- Self-installed filters in the suction line must be approved beforehand by HAWE Hydraulik.
- A system pressure-limiting valve must be installed in the pressure line so that the maximum system pressure is not exceeded.

5.2.2 Connections

The connecting lines' nominal width depends on:

- the given usage conditions
- viscosity of the hydraulic fluid
- start-up and operating temperature
- pump speed

HAWE recommends: Use hose lines (improved damping characteristics) instead of rigid pipelines.

Pressure connection	 The pressure connection on type V60N-060 is established via a threaded connection G 3/4"; on type V60N-090/110/130 via a threaded connection G 1". Observe the fitting manufacturers' specified tightening torques. 							
Suction port	the max. deliventhe following to	 The suction port on all pumps is established via standardised suction intakes with a size which depends on the max. delivery flow of the pump. The specified max. delivery flow Qmax must be observed. It is listed in the following table. Nominal width (N) 38 (1 1/2") 42 50 (2") 64 (2 1/2") 76 (3") 6 (1 1/4) 7 (1 1/2) 						
	Q _{max} (lpm)	Q _{max} (lpm) 75 90 125 190 250 90 125						
	 The suction intakes can be ordered as an option with the pump. If possible, route the suction line to the tank on a rising gradient. This allows trapped air to escape. Observe the notes on installation see Chapter 5.2.3, "Installation positions". The absolute suction pressure must not fall below 0.85 bar. 						scape.	



Drain port

- The pump features 2 drain ports G 3/4" or 1 1/16-12-UN-2B. A G 1/8" threaded connection is also available for the flange version SAE-B2, SAE-B4 and SAE-4. This is used for bleeding in the case of vertical installation positions.
- The nominal width of the leakage line must not be less than 16 mm. The cross-section is determined by the max. permissible housing pressure.
- Integrate the leakage line in the system in such a way as to prevent direct connection with the suction line of the pump.
- All drain ports can be used simultaneously.
- A separate leakage line from the controller to the tank is not required.
 Observe the notes on installation see Chapter 5.2.3, "Installation positions".
- Do not install a check valve in the leakage line!

LS port for LSP, LSPT, LSNR, LSNRT variants

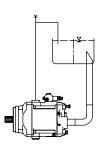
- The LS line is connected to the controller via a G 1/4" threaded connection.
- The nominal width of the line depends on the mounting position of the pump and should be 10 % of the pressure line capacity. A hose line should generally be used in preference to a rigid pipe connection.
- When the proportional directional spool valve is in a neutral position, the LS line must always be fully relieved (only controller type LSP, LSNR)! For controller type LSPT, LSNRT relief occurs within the controller.

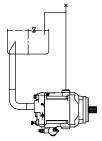
5.2.3 Installation positions

The variable displacement axial piston pump can be mounted in any installation position.

Horizontal installation

► For horizontal installation, use the uppermost drain port.



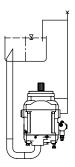


Vertical installation

Pump below the min. fill level

- ► Mount the pump so that the pump mounting flange is facing upwards.
- ► For vertical installation, use the uppermost drain port.
- ► Also connect the G 1/8" bleeding port to the pump flange (see Chapter 4, "Dimensions").
- ► Take appropriate measures to ensure continuous venting of this line (line routing/venting).

For installation with pump flange facing downwards: Get in touch with HAWE Hydraulik SE.

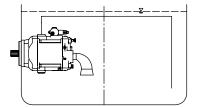


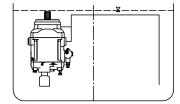


5.2.4 Tank installation

Pump below the min. fill level

The pump can be operated either with or without a suction intake. Using a short suction intake is recommended.





Pump above the fill level



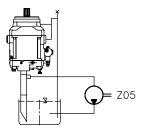
DAMAGE

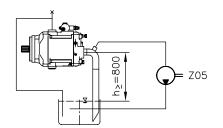
The pump must not run dry via the pressure, intake, drain, venting or control lines. This applies in particular to long periods of downtime.

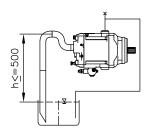
- ► The leakage line must be installed in the tank in such a way that it ends below the oil level.
- Facilitate venting of connecting lines via separate vent openings.
- Adjust the venting sequence to suit the specific installation.
- ► If necessary, a gear pump should be provided in order to draw air from the suction line.

Contact form for special consultation on axial piston pump design:

Checklist for variable displacement axial piston pump design: B 7960 checklist







For further information on installation, operation and maintenance, see the relevant assembly instructions: B 7960, B 5488.

5.3 Operating instructions

Observe product configuration and pressure/flow rate.

The statements and technical parameters in this document must be strictly observed.

The instructions for the complete technical system must also always be followed.



DAMAGE

- ► Read the documentation carefully before usage.
- ► The documentation must be accessible to the operating and maintenance staff at all times.
- ► Keep documentation up to date after every addition or update.





⚠ CAUTION

Overloading components due to incorrect pressure settings.

Risk of minor injury.

- Pay attention to the maximum operating pressure of the pump and the valves.
- Always monitor the pressure gauge when setting and changing the pressure.

Purity and filtering of the hydraulic fluid

Fine contamination can significantly impair the function of the product. Contamination can cause irreparable damage.

Examples of fine contamination include:

- Swarf
- Rubber particles from hoses and seals
- Dirt due to assembly and maintenance
- Mechanical debris
- Chemical ageing of the hydraulic fluid



DAMAGE

New hydraulic fluid from the manufacturer may not have the required purity.

Damage to the product is possible.

- ► Filter new hydraulic fluid to a high quality when filling.
- ▶ Do not mix hydraulic fluids. Always use hydraulic fluid that is from the same manufacturer, of the same type, and with the same viscosity properties.

For smooth operation, pay attention to the cleanliness level of the hydraulic fluid (cleanliness level see Chapter 3, "Parameters").

Additionally applicable document: D 5488/1 Oil recommendations

Restrictions in operation during cold start phase and warm-up phase

Phase	Temperature	Viscosity (mm ² /s)
Cold start phase	-25 to -40°C	< 1000
Warm-up phase	-25 to 80 °C	500 to 1000
Normal operation	-25 to 80 °C	10 to 500



DAMAGE

Optimum range: 16 - 60 mm²/s

Cold start phase:

- $p_B = 20 30 \text{ bar}$
- n ≤ 1000 rpm

Warm-up phase:

- $p_B = 20 200 \text{ bar}$
- n ≤ 1500 rpm

Normal operation:

No further restrictions. Operating conditions see Chapter 3, "Parameters".



5.4 Maintenance information

This product is largely maintenance-free.

Check regularly (at least once a year) by visual inspection whether the hydraulic connections are damaged. If external leakages are found, shut down and repair the system.

Clean the surface of the device regularly (at least once a year) (dust deposits and dirt).



6

Other information

6.1 Accessories, spare and individual parts

To purchase spare parts, please see HAWE Hydraulik interactive contact map.

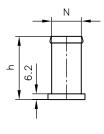
6.1.1 Suction intake

Ordering example:

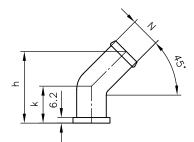
V60N - 090 R DY N - 1 - 0 - 01/LSP - 350 - A00/76

Nominal width (N) Qmax (lpm)	Flow rate	e Geometric shape									
		Straigh		45°		Order	90°		Order	Thread	Order
	(4)/	A00/	number	A45/	••	number	A90/		number	Α.	number
				h	k	_	h	k	_	h	_
38 (1 1/2")	75	65	79 93336 00	-	-	-	53	70	79 93344 00	-	-
42 (1 5/8")	90	-	-	85	40	79 93340 00	-	-	-	-	-
50 (2")	125	65	79 93337 00	96	40	79 93341 00	53	84	79 93345 00	-	-
64 (2 1/2")	190	90	79 93338 00	96	40	79 93342 00	109	129	79 93346 00	-	-
76 (3")	250	106	79 93339 00	106	40	79 93343 00	-	-	-	-	-
7 (1 1/2")	125	-	-	-	-	-	-	-	-	28,5	79 40719 00
7 UNF (7/8-12 UN-2B)	125	-	-	-	-	-	-	-	-	28,5	79 41599 00

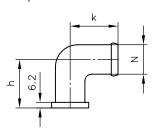




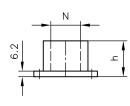
45/...



A90/...



Α7



The attachment kit for suction intake (included) comprises:

- 4x hex bolts M8x16-8.8
- 0-ring 44.2x3 NBR 70 Sh
- 2 mounting flange halves

(Order no. 79 93355 00)



NOTE

Use nominal width 38 (1 1/2") for reduced displacement volume only!

Installation information see Chapter 5, "Installation, operation and maintenance information"

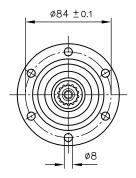


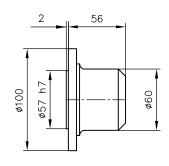
6.1.2 Coupling flange for cardan shafts

Special coupling flanges for cardan shafts (Ø100-6-Ø8) according to ISO 7646.

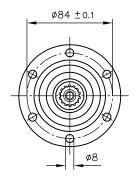
For telescopic cardan shafts also with spacer ring and connecting screw for attachment to the drive shaft of the pump.

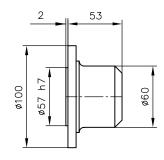
Coding SAE-C, SAE-CS





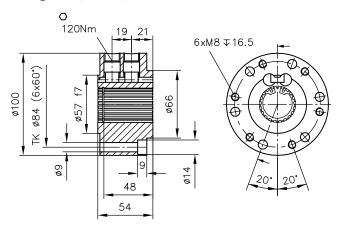
Coding DIN ISO 014





Coding	Spline profile	Order number
SAE C	14T 12/24 DP	79 29555 00
SAE CS	21T 16/32 DP	79 42793 00
DIN ISO 14	B8 x 32 x 36	79 29709 00

Coding SAE-C, SAE-CS, DIN ISO 014



Coding	Spline profile	Order number
SAE-C	14T 12/24 DP	79 94495 00
SAE-CS	21T 16/32 DP	79 94479 00
DIN ISO 14	B8 x 32 x 36	79 94496 00



6.2 Planning information

Determination of nominal sizes

Delivery flow	$Q = \frac{V_g \cdot n \cdot \eta_V}{1000} (I/\min)$		= Flow rate (lpm)
			= Torque (Nm)
Drive torque	$M = \frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_{mh}} (Nm)$	Р	= Power (kW)
$M = \frac{1}{20 \cdot \pi \cdot \eta_{mh}} (NM)$	$m = 20 \cdot \pi \cdot \eta_{mh}^{(NIII)}$	Vg	= Geom. output volume (cm³/rev.)
Drive power	$P = \frac{2\pi \cdot M \cdot n}{60000} = \frac{Q \cdot \Delta p}{600 \cdot \eta_t} (kW)$	Δр	= Differential pressure
		n	= Speed (rpm)
			= Volumetric efficiency
		η_{mh}	= Mechanical-hydraulic efficiency
		ηt	= Overall efficiency ($\eta_t = \eta_V \cdot \eta_{mh}$)



References

Additional versions

- Variable displacement axial piston pump type V80M: D 7962 M
- Variable displacement axial piston pump type V30E: D 7960 E
- Variable displacement axial piston pump type V30D: D 7960
- variable displacement axial piston pump type C40V: D 7964
- Fixed displacement axial piston pump type K60N: D 7960 K
- Axial piston motor type M60N: D 7960 M
- Proportional directional spool valve type EDL: D 8086
- Proportional directional spool valves types PSL, PSV size 2: D 7700-2
- Proportional directional spool valves types PSL/PSV/PSM, size 3: D 7700-3
- Proportional directional spool valve, type PSL, PSM and PSV size 5: D 7700-5
- Proportional directional spool valve type PSLF, PSVF and SLF size 3: D 7700-3F
- Proportional directional spool valve type PSLF, PSVF and SLF size 5: D 7700-5F
- Proportional directional spool valve banks type PSLF and PSVF size 7: D 7700-7F
- Load-holding valve type LHT: D 7918
- Load-holding valve type CLHV: D 7918-VI-C
- Load-holding valve type CLHV: D 7918-VI-PIB
- Load-holding valve type LHDV: D 7770
- Proportional amplifier type EV1M3: D 7831/2
- Proportional amplifier type EV1D: D 7831 D
- Proportional amplifier type EV2S: D 7818/1

observe operating instructions

General operating manual for the assembly, initial operation and maintenance of hydraulic components and systems: B 5488

